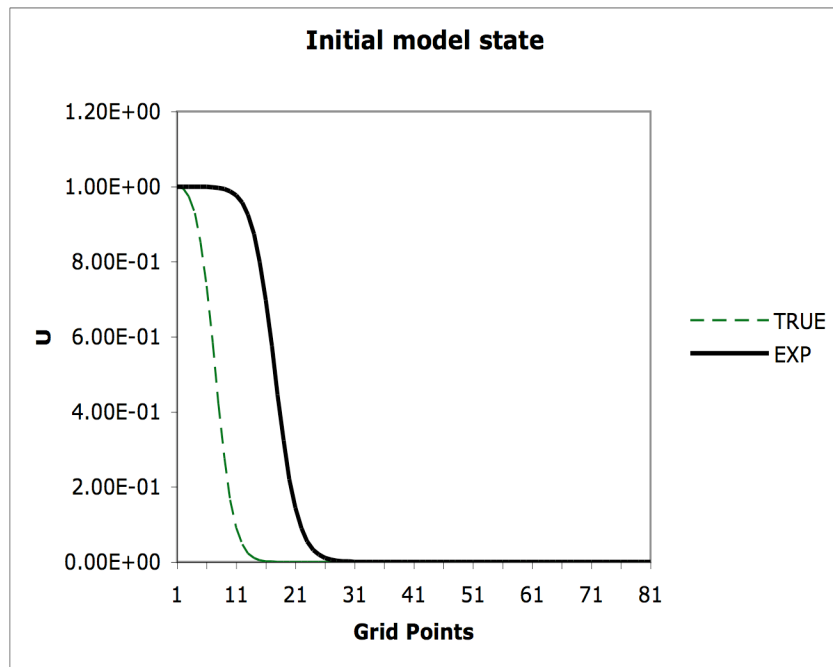


# Non-differentiable observation operator in MLEF minimization

1-d Burgers model simulating a shock-wave

- ◆  $N_{state}=81$
- ◆  $N_{obs}=81$  (simulated observations)

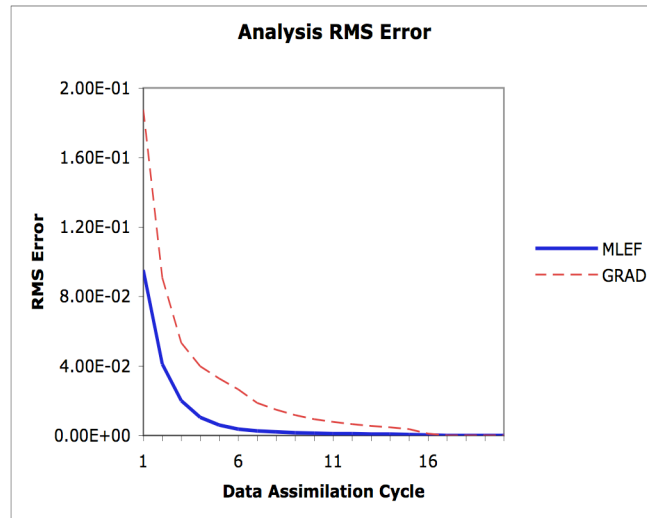


$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} = \nu \frac{\partial^2 u}{\partial x^2}$$

## Non-differentiable observation operator

$$H(x) = \begin{cases} x^3 & \text{for } x \geq 0.5 \\ -x^3 & \text{for } x < 0.5 \end{cases}$$

Discontinuity in the function  
and all its derivatives

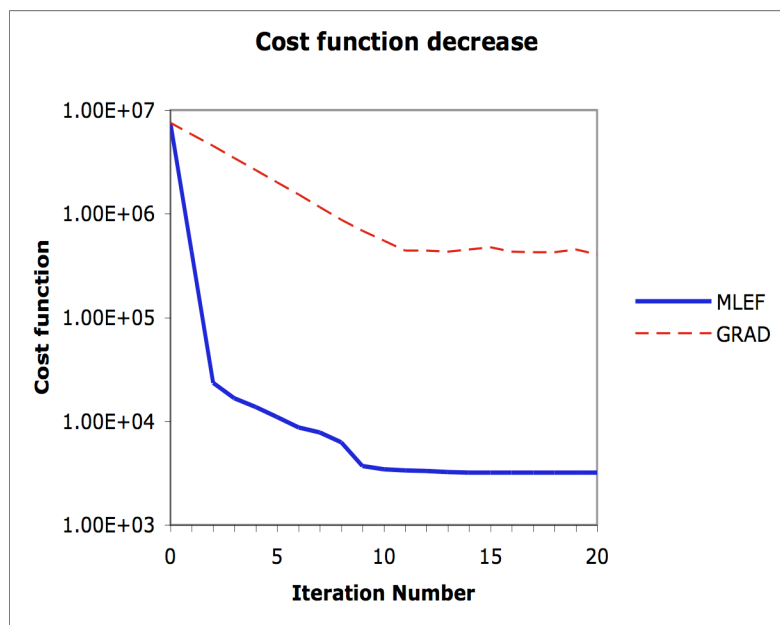


**Analysis RMS error in the MLEF  
and GRAD experiments**

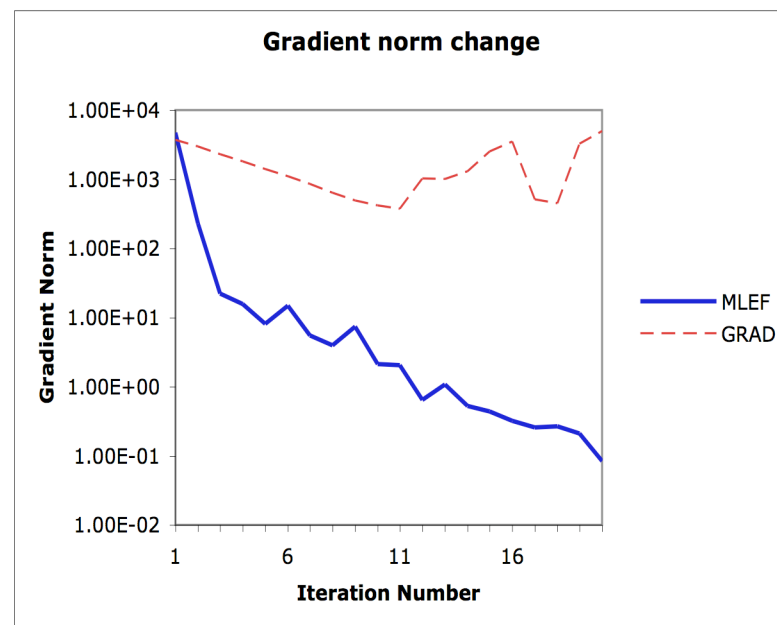
**MLEF**  $H(x + p_i^f) - H(x)$

**GRAD**  $\left( \frac{\partial H}{\partial x} \right) p_i^f$

## MLEF vs. gradient-based minimization (GRAD)



**Cost function**



**Gradient norm (GRAD)**

**Generalized Gradient norm (MLEF)**

- Cost function and “gradient” norm show the benefit of the generalized conjugate-gradient minimization (MLEF)