

# **EnKF testing at NCEP**

## ***preliminary results***

Thorpex Ens DA conf call: 10/04/2007  
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# Experimental Design

- **test period:** May and June 2007 (only May 8-May 23 done so far).
- **observations used:** all prepbufr, GPS ,AMSU radiances (exclude AIRS, HIRS etc. for now).
- **resolution:** T126L64 (256x128x64 analysis grid)
- **ensemble size:** 64
- **benchmark:** GSI, same resolution and observation set.

# EnKF implementation

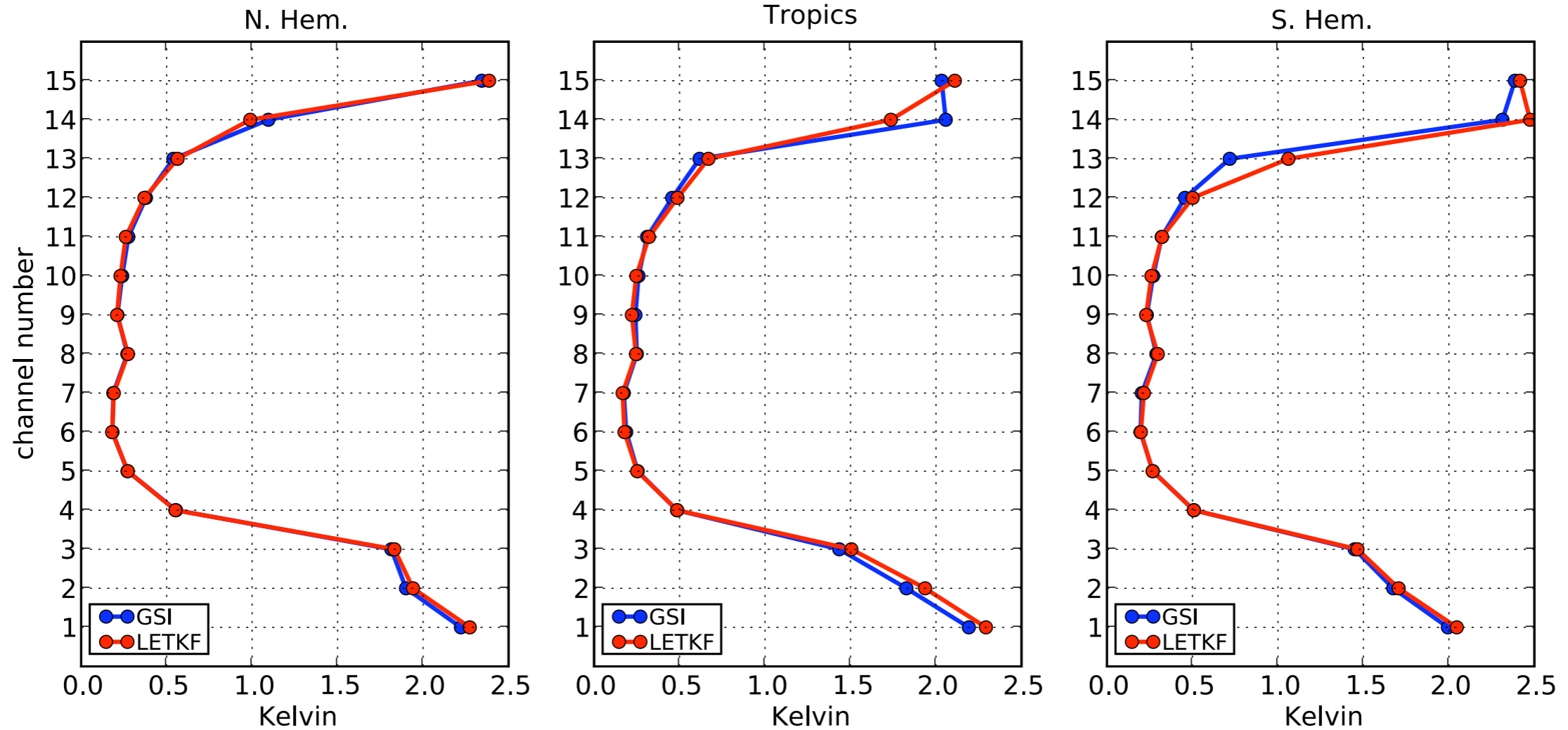
- both serial EnSRF ('Potter' update) and LETKF.
- radiance bias correction a la GSI.
- Radius of influence for obs: 1400 km, 1 scale height (  $\log(\text{pressure})$  ). Linear tapering.
- covariance inflation (20%), plus 0.3 x random sample of reanalysis tendencies.

# Computation Cost: Serial EnSRF vs LETKF

- parallelization:
  - scales nearly linearly for both, EnSRF has more communications overhead.
- cost as a function of ensemble size (K) and observation count (L).
  - $O(K^2L)$  for LETKF
  - $O(L^2K)$  for EnSRF
  - $K=64, L=700K, 32$  processors: EnSRF takes  $\sim 7000$  seconds, LETKF  $\sim 3000$  seconds. Strong function of observation influence radius.

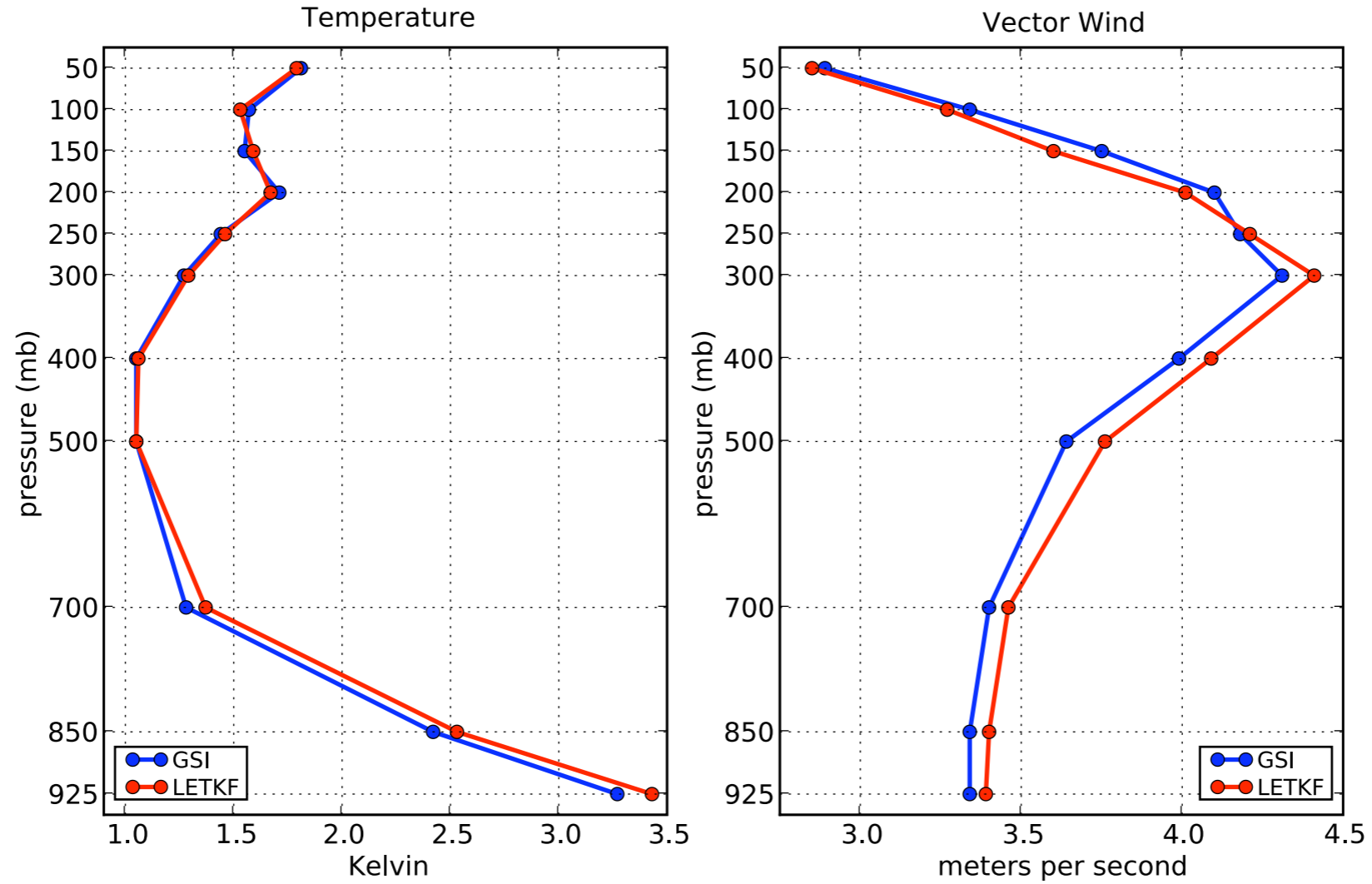
# O-F statistics (AMSUA)

O-F AMSUA Brightness Temperatures 2007051400-2007052212



# O-F statistics (Sondes, Ps)

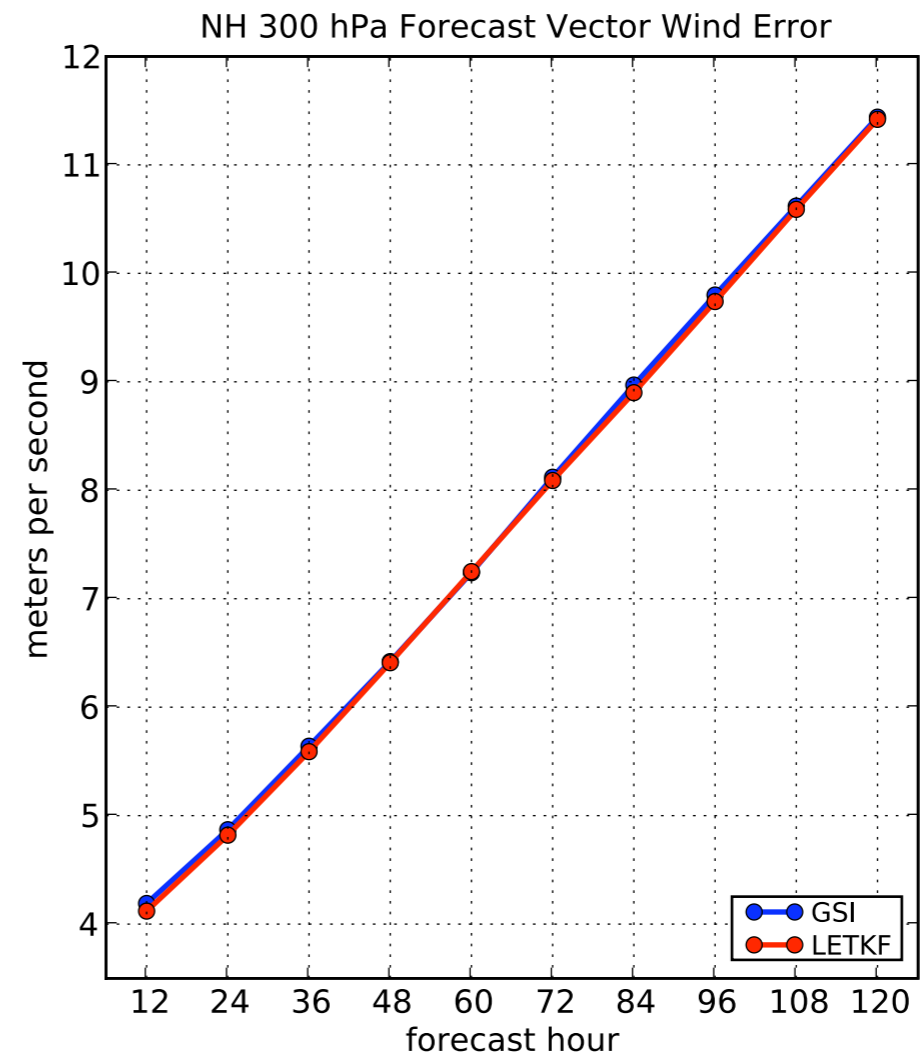
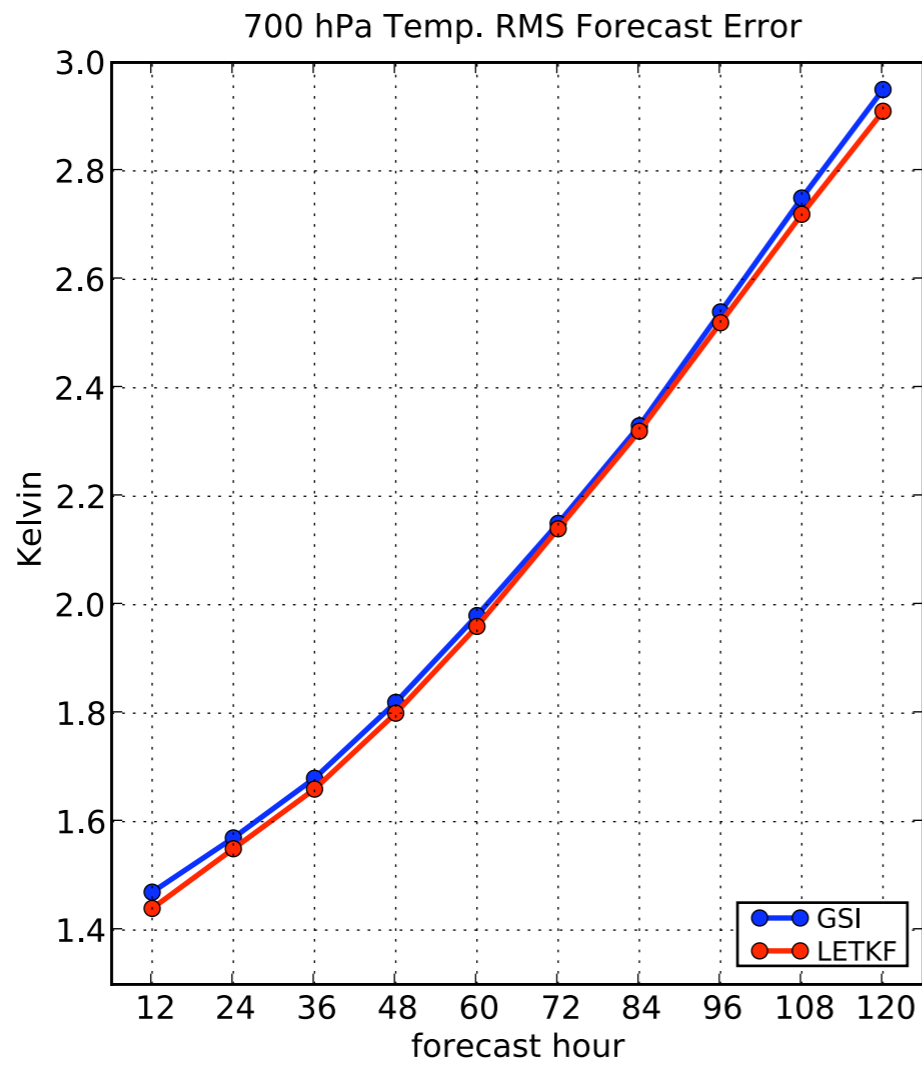
O-F Radiosondes 2007051400-2007052212



<b><i>Ps O-F</i></b>	<b><i>NH</i></b>	<b><i>TR</i></b>	<b><i>SH</i></b>	<b><i>Global</i></b>
<b>LETKF</b>	<b>1.14</b>	<b>1.26</b>	<b>1.28</b>	<b>1.17</b>
<b>GSI</b>	<b>1.14</b>	<b>1.34</b>	<b>1.28</b>	<b>1.18</b>

# Forecast Skill *relative to UKMET analyses*

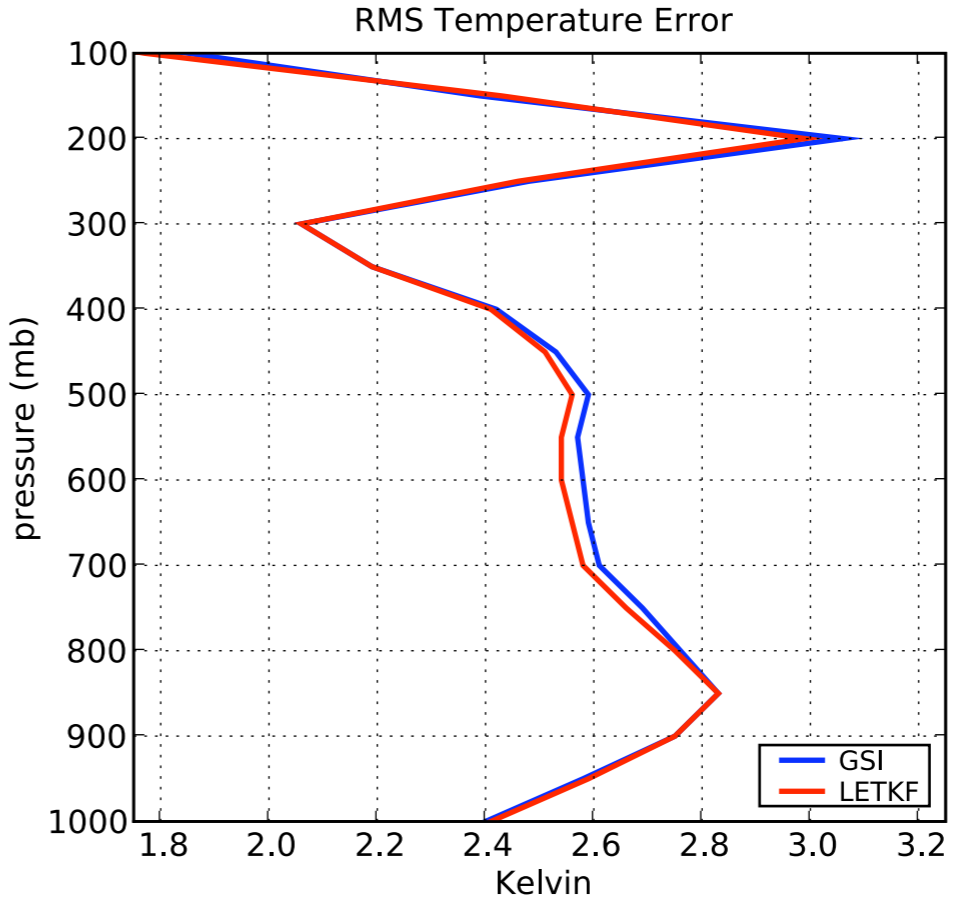
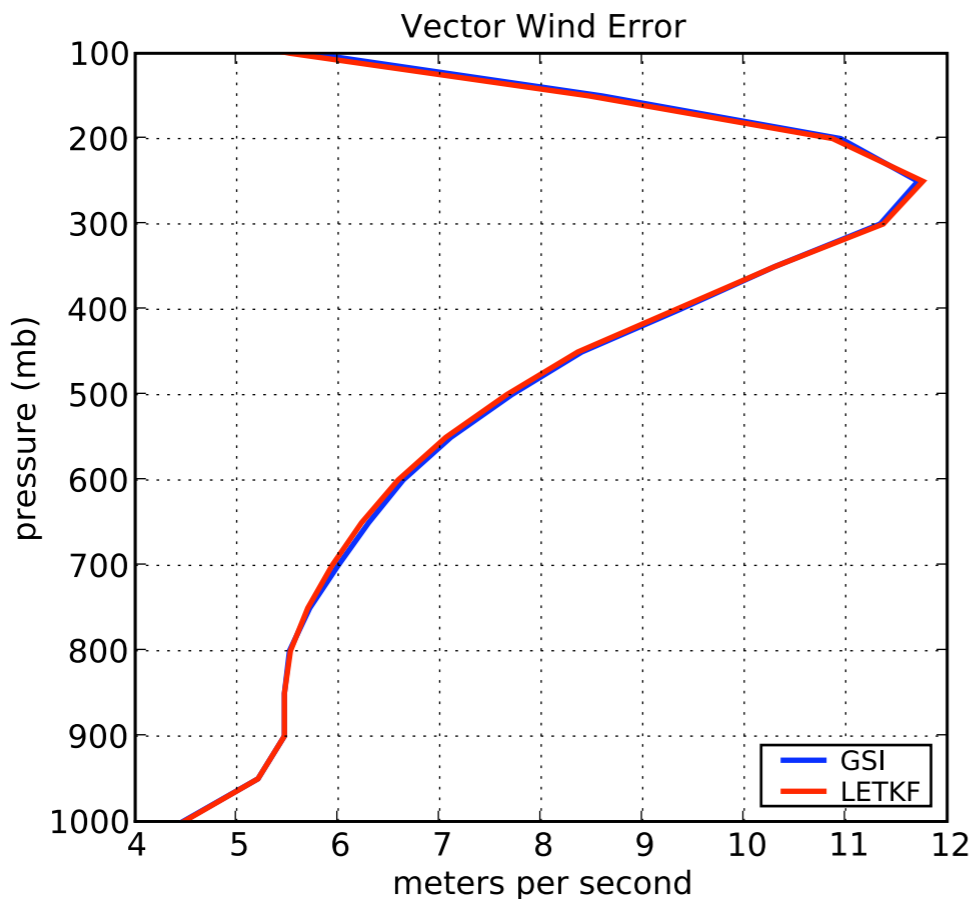
Forecasts initialized 2007051400-2007052212, verified against UKMET analyses



# 5-day Forecast Skill

## *relative to operational GDAS analysis*

120-h Forecasts initialized 2007051400-2007052212, verified against operational GDAS1 analysis

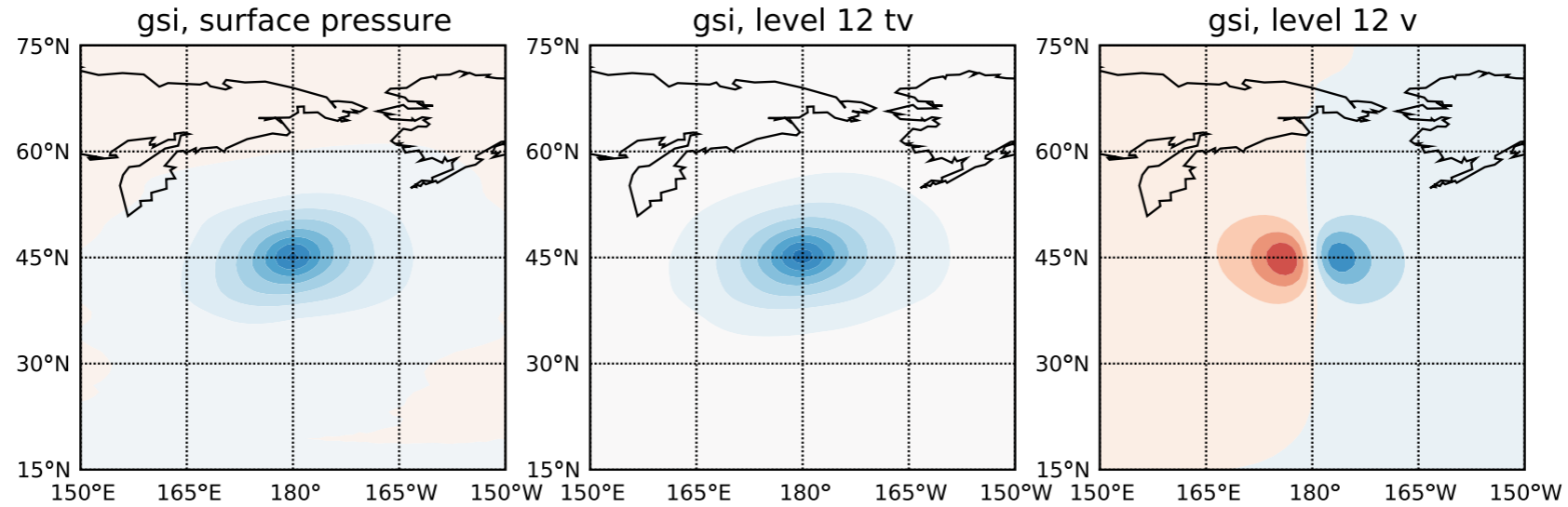




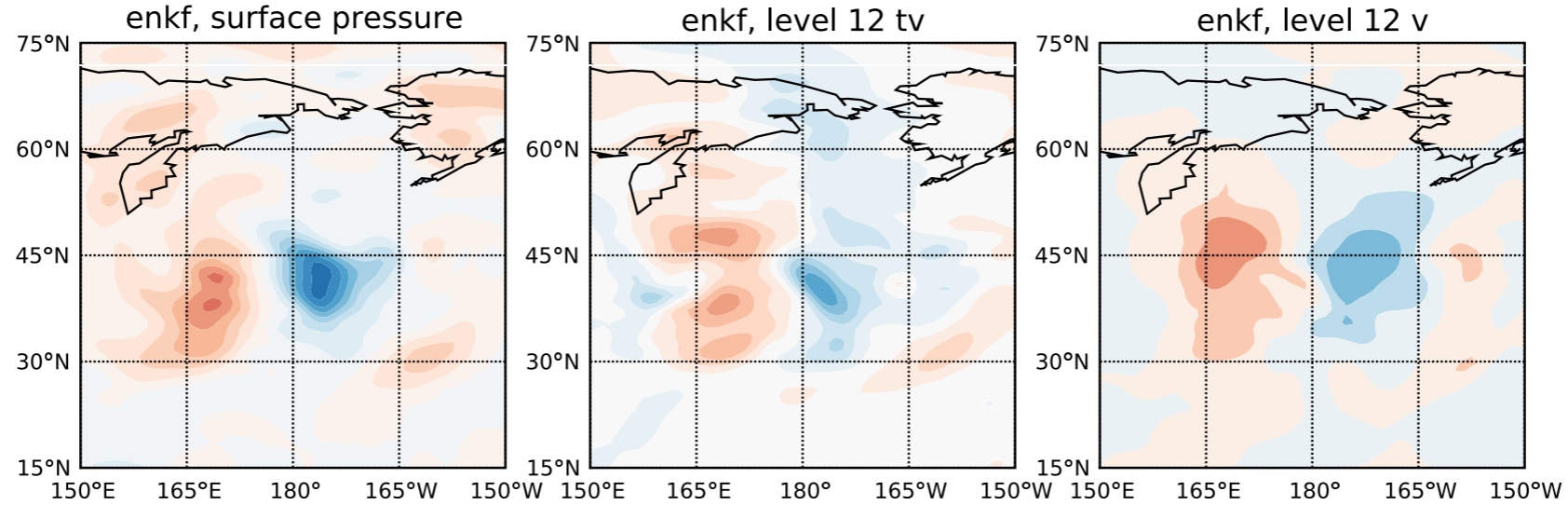
# Single Ob Increments

single ps ob at 45N, 180W, 1mb lower than background, 1mb error

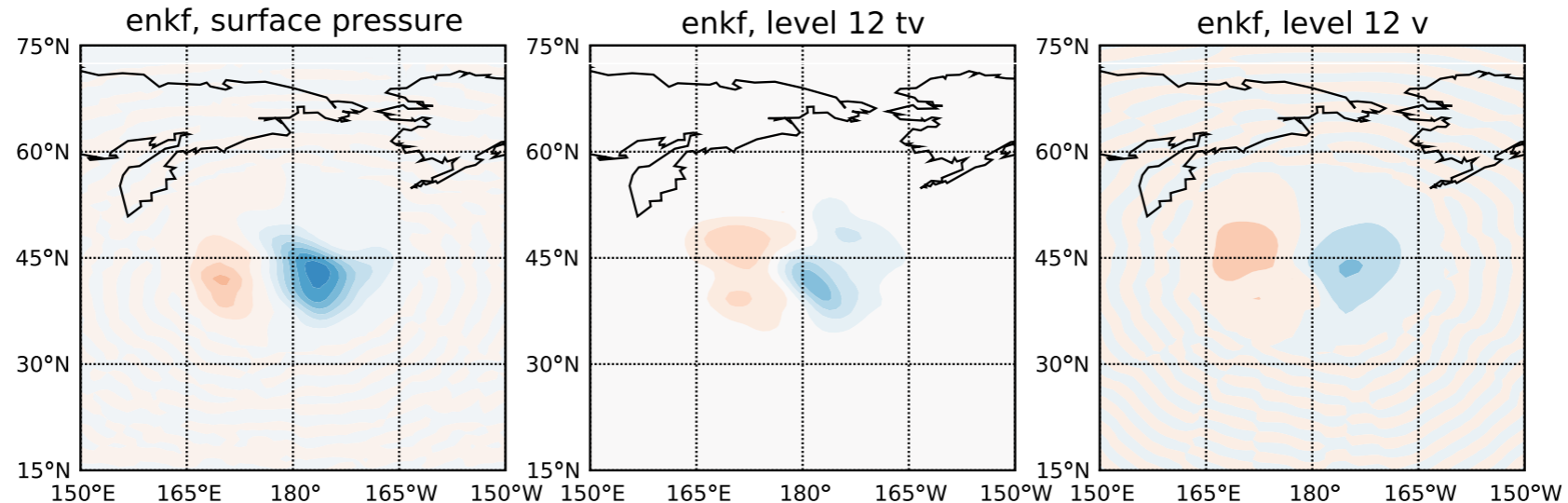
**GSI**



**LETKF**  
*no localization*



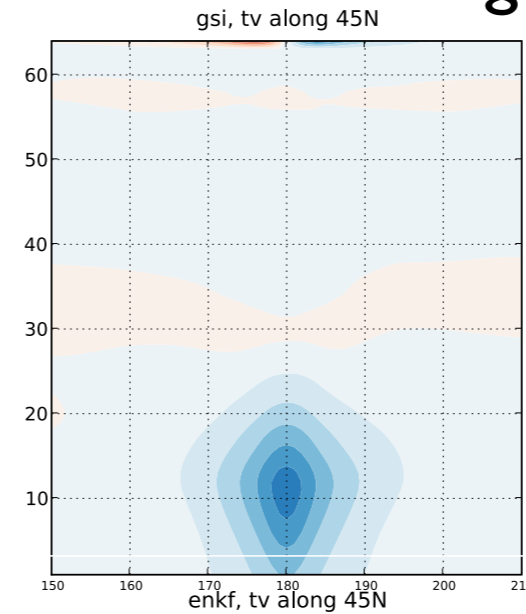
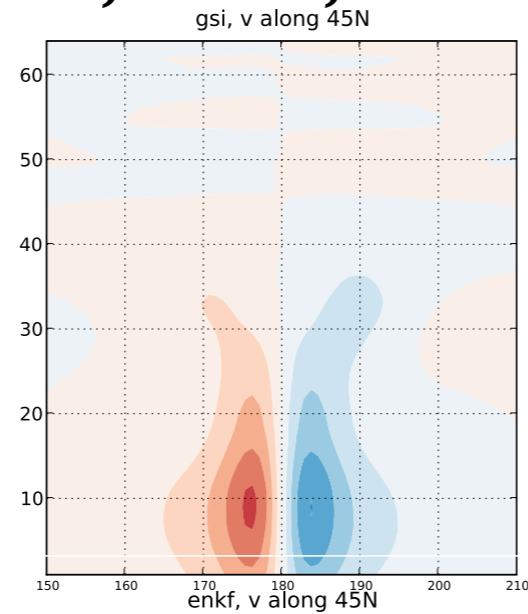
**LETKF**  
*1400 km localization*



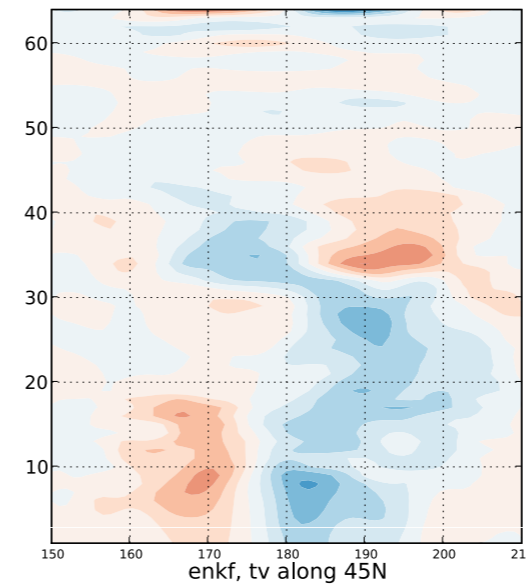
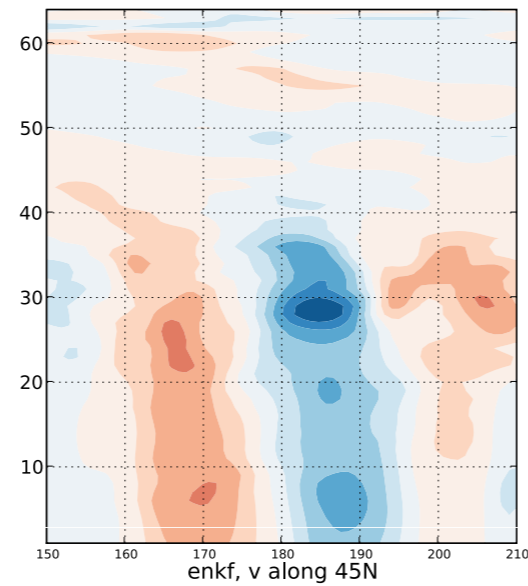
# Single Ob Increments (cont.)

single ps ob at 45N, 180W, 1mb lower than background, 1mb error

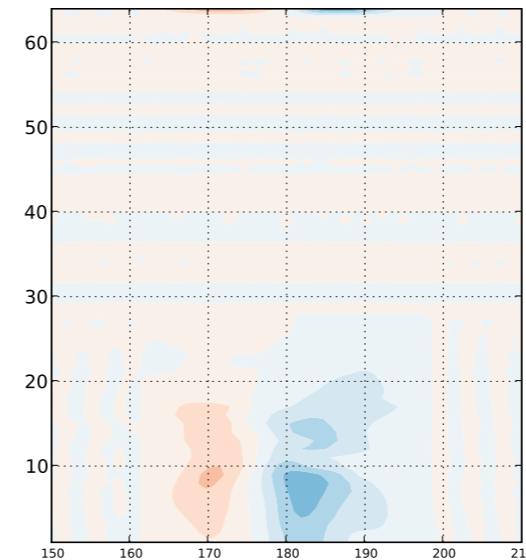
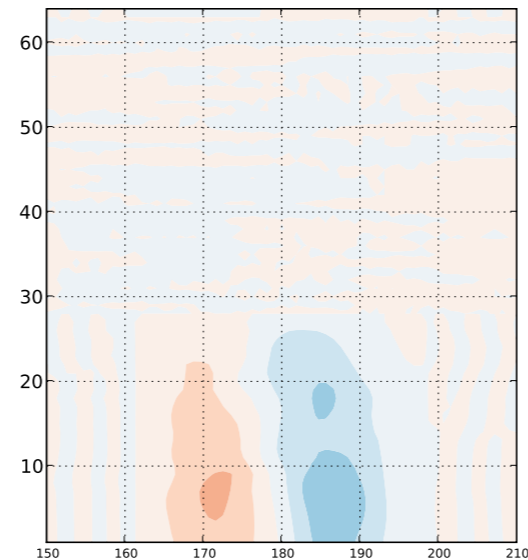
**GSI**



**LETKF**  
*no localization*



**LETKF**  
*1 scale height  
localization*



# TODO List

- More tuning.
- Better (more refined) localization scheme?
- Better 'system error' parameterization, bias correction?
- Higher resolution? Larger ensemble?
- ????