# Ensemble Forecasting with the NCEP coupled ocean-atmosphere model

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## The NCEP coupled model: CFS

- Created to produce dynamical seasonal forecasts
- Couples the GFS (atmosphere & Land) with MOM (ocean)
- Several versions of the coupled model
- Routine ocean, land, and atmosphere forecasts out to 10 months
- Operational CFS: released in 2004
- GFS (T62L64) operational in 2003
- MOM v3 (40 levels, 0.5° in the equator and 1° poleward)
- Sea-Ice: climatology
- New CFS: to be released in 2011
- GFS (T126L64) v. 2009
- MOM v4 (40 levels, .25 in the equator and .5 poleward)
- Global Sea-Ice Model

More information and data are posted at: http://cfs.ncep.noaa.gov

## CFS03 (old, operational) Model

#### Atmosphere: GFS03 T62L64, Ocean: GFDL's MOMv.3



Adequate simulation of the intraseasonal-to-interannual SST variability to carry out successful seasonal ensemble forecasting

## **Operational Ensemble scheme**

- Lagged ensemble
- Four forecasts per day
- Ensemble can be created by collecting the last 30-60 forecasts
- Ensemble forecasts are bias corrected via a long hindcast dataset
- Forecast quality is as good as or better than statistical methods



### **Coupled ensemble schemes: what we know**

- The slow growing mode (associated with ocean) can be captured with the Breeding scheme when
  - a) The rescaling time period is sufficiently long as to allow the fast mode to saturate and
  - b) The rescaling factor is computed from a slow-evolving ocean variable (e.g. SST in the tropical Pacific)
- In both the ZC model (Cai et al 2002) and the NSIPP (Yang et al 2004) coupled models, the breeding method captures the ENSO mode
- Breeding scheme better than random perturbations for seasonal to intraseasonal forecasts (Yang et al. 2008).
  NASA operational coupled model uses this scheme for its ensemble generation.

## **Perfect model experiments**



dx0: Amplitude of the initial perturbation ~10% of climatological s.d. over Pacific region

 $\mathbf{R} = 5,15,30$  days, rescaling time period



$$P_t = C_t + f * (F_{t-\tau \to t} - C_t)$$

Where C is the control field, F is the forecast valid at t.

$$f = \frac{0.1^{o} C}{\left\| SST - SST_{c} \right\|_{TropPacific}}$$

#### Surface and subsurface error in T



## **CTB funded project**

- In collaboration with Schubert et al (NASA-GSFC) CPC and UMD (Kalnay).
- Objective: Create an operational ensemble forecast system for subseasonal time scales.



- Current GFS coupled with MOM4
- All variables are perturbed in each level
- 80 ET perturbations each 6 hrs
- Once a day 20 perturbations will be integrated forward out to 45 days and 60 out to 16 days

### **CTB PROPOSAL WITH SCHUBERT ET AL**

	GEFS	CFS	Proposed
Model	Atmosphere forced by damped persistent SSTA	Coupled OLA	Coupled OLA
Initial Conditions	<b>GDAS</b> (Best available)	CDAS (sub-optimal) and GODAS (best available)	GDAS and GODAS Best available
Ensemble initialization	Ensemble Transform (State-of-the-art scheme; No information on uncertainty in lower boundary conditions)	Lagged (Not centered on the latest and best analysis; Initial variance not controlled)	Ensemble Transform/Breeding (State-of-the-art scheme. Incorporates uncertainty of lower boundary conditions)
Ensemble Size (per initial time)	20 members	1 member (sub-optimal performance)	20 members
Length of Forecast	16 days	10 months	Up to 45 days
Generation of hindcasts	Best DA/model/ensemble scheme (Allows periodic DA/models/ensemble improvements)	Frozen DA/model/ensemble scheme (Sub-optimal performance)	Real Time Hindcast (Allows periodic DA/model/ensemble improvements)
Sample for bias correction	Most recent season (sub- optimal for longer led times)	Large set of hindcasts (Allows high quality bias correction for long leads)	Large set of hindcasts (Allows high quality bias correction for long leads)
DA/model/ensem ble update frequency	~ 1 per year	~ 1 per 7 years	~ 1 per year

Blue colors indicate desirable features

## Remarks

• Diagnostics of current operational ensemble (lagged) scheme deteriorates the skill of prediction at least for the short range forecasts

• Search for the best scheme suitable to the operational computer conditions.

• A research version of the CFS is being made available to assess ensemble schemes. The coupled model, however is not currently under the ESMF framework to easily incorporate to operations.

• Two teams have been formed. One to work on the numerical and another on the scientific issues.