



Overview of Hydrologic Ensemble Prediction Activities at the Office of Hydrologic Development

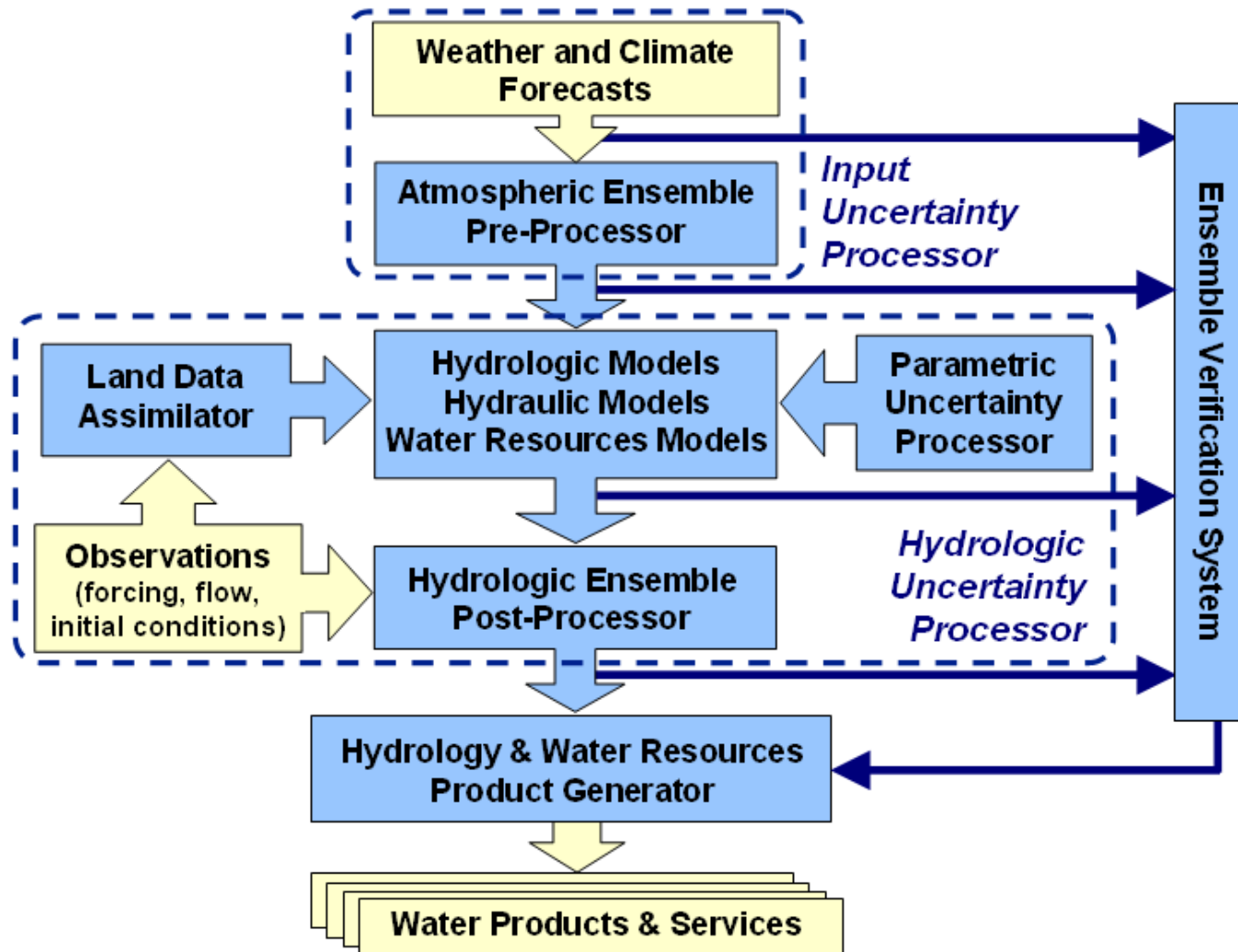
Julie Demargne^{1,2}, Limin Wu^{1,3}, James Brown^{1,2}, Satish Regonda^{1,4}, Yuqiong Liu^{1,4}, and Haksu Lee^{1,2}

Acknowledgements to D.J. Seo and John Schaake

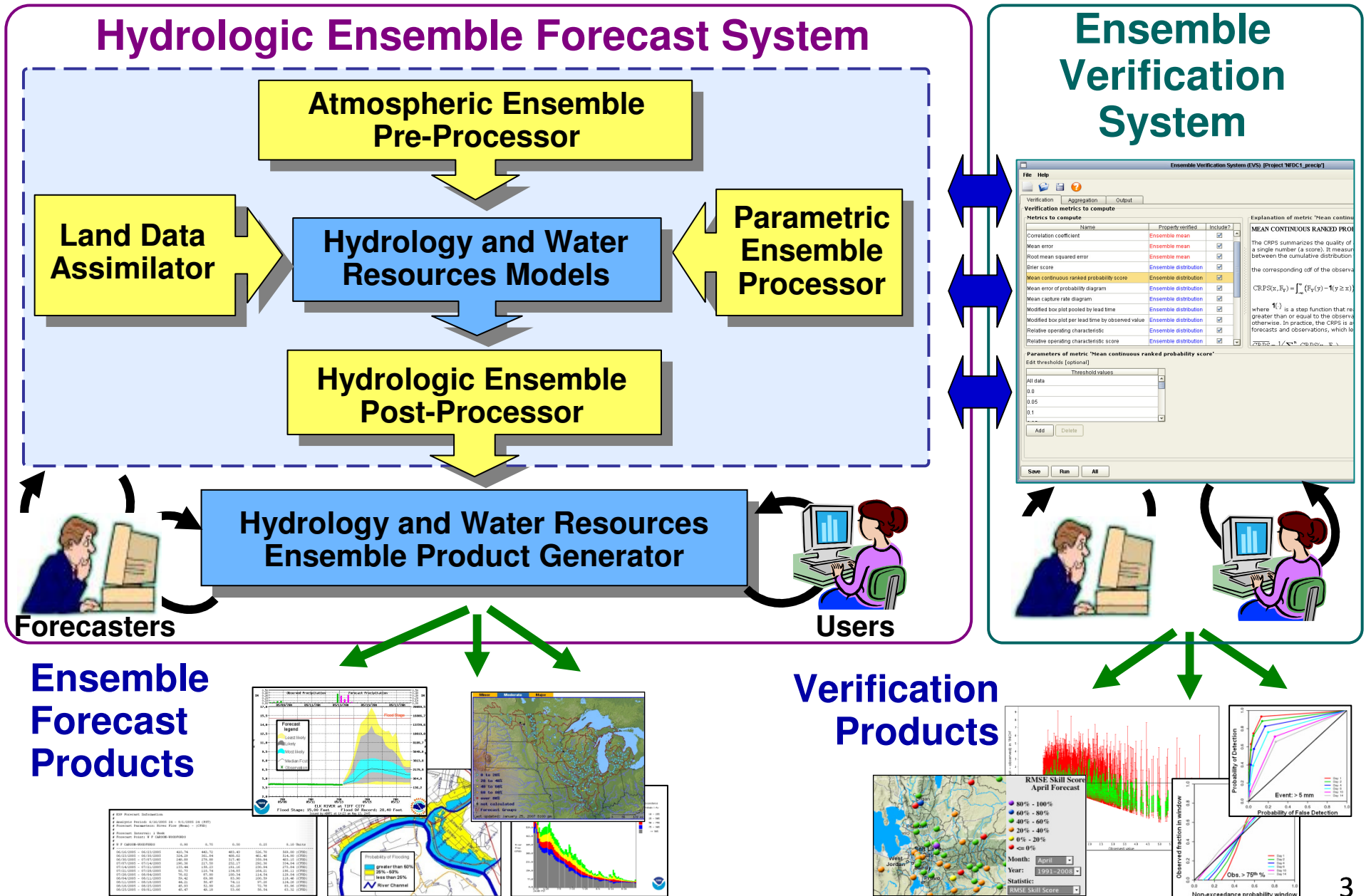
1. NOAA/NWS Office of Hydrologic Development
2. University Corporation for Atmospheric Research
3. TCoombs & Associates, LLC
4. Riverside Technology, Inc.

Main objective

- Develop a hydrologic ensemble forecast system to account for all major sources of uncertainty and communicate uncertainty-quantified forecast and verification information to end users



Hydrologic Ensemble Forecast Service (HEFS)



Towards Water Resources Service

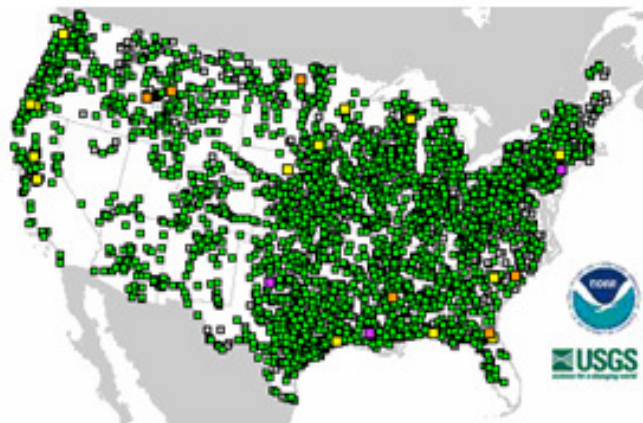
Predicting Floods to Droughts

In Your Neighborhood

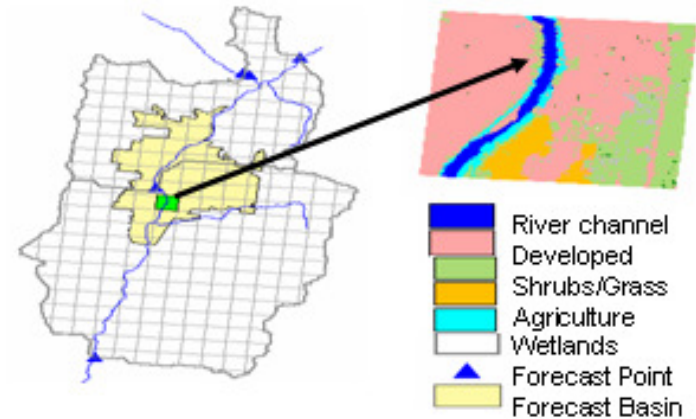
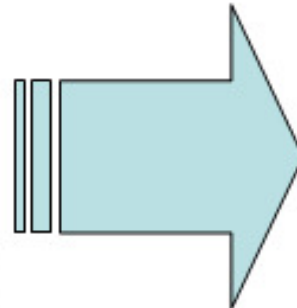


River Services

(600 miles per forecast point)

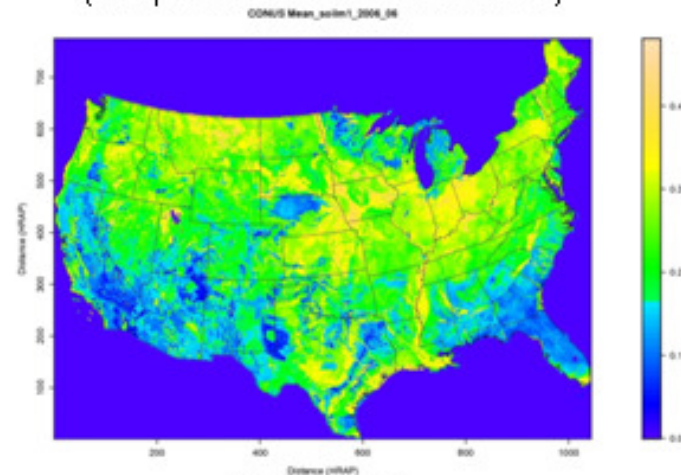


River Conditions



Water Resource Services

(6 square mile forecast basins)



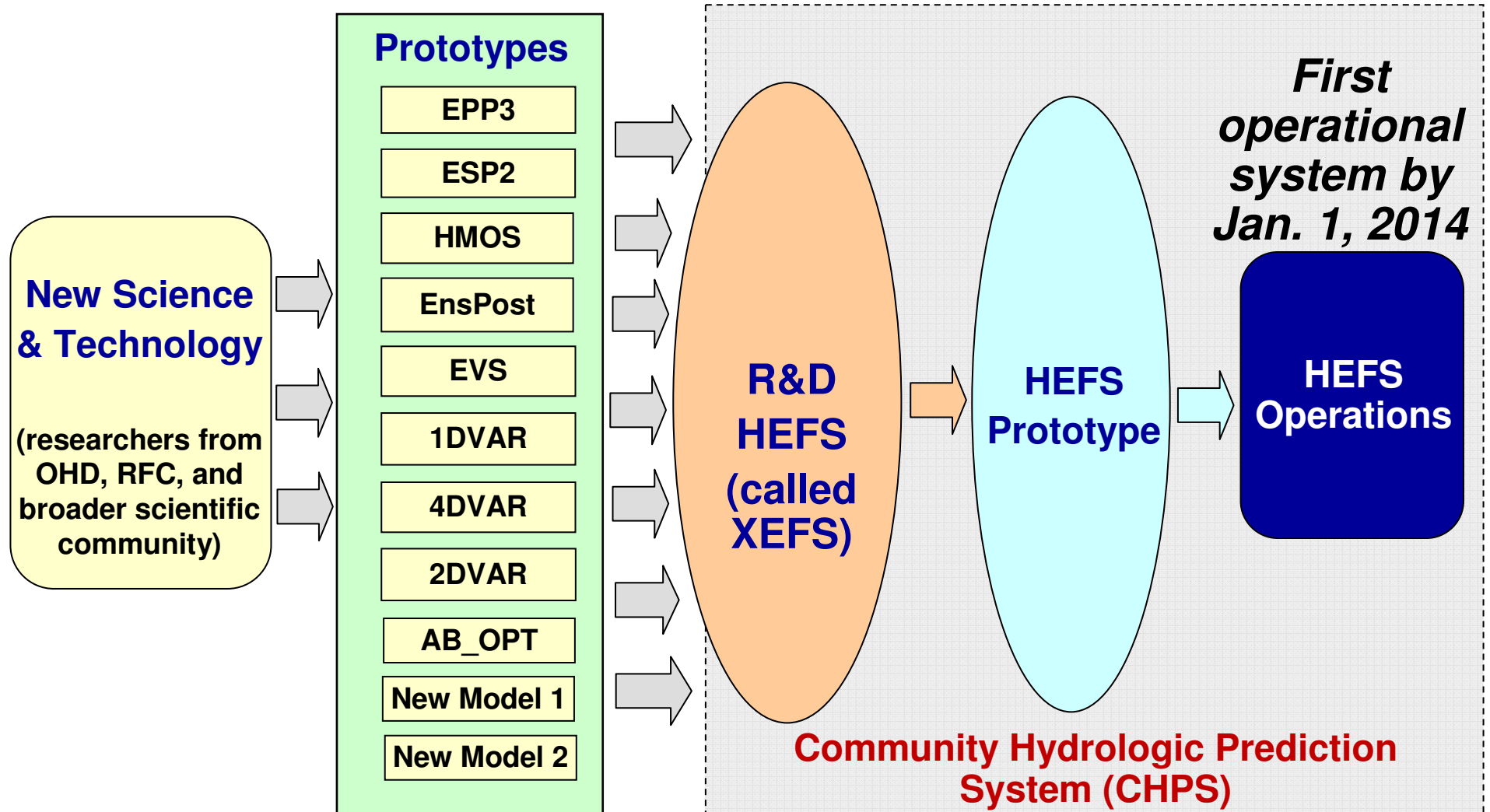
Soil Conditions

From Carter (2006)

Ensemble Prediction: Current (Seasonal) Ensemble Streamflow Prediction vs. HEFS

Feature	Current	HEFS
Platform	National Weather Service River Forecast System (NWSRFS) (inflexible, outdated)	Community Hydrologic Prediction System (CHPS) (flexible, open architecture)
Forecast horizon	Weeks to seasons	Hours to years
Input forecasts	Climate outlook forecasts	Short-, medium- and long-range forecasts (HPC/RFC, GFS/GEFS, CFS/CFSv2, SREF, others)
Hydrologic uncertainty	Not addressed	Addressed (but w/ room for improvement)
Products	Limited number of graphical products	A wide array of user-tailored products via Web-enabled interactive toolbox

Collaborative R&D and RTO for HEFS

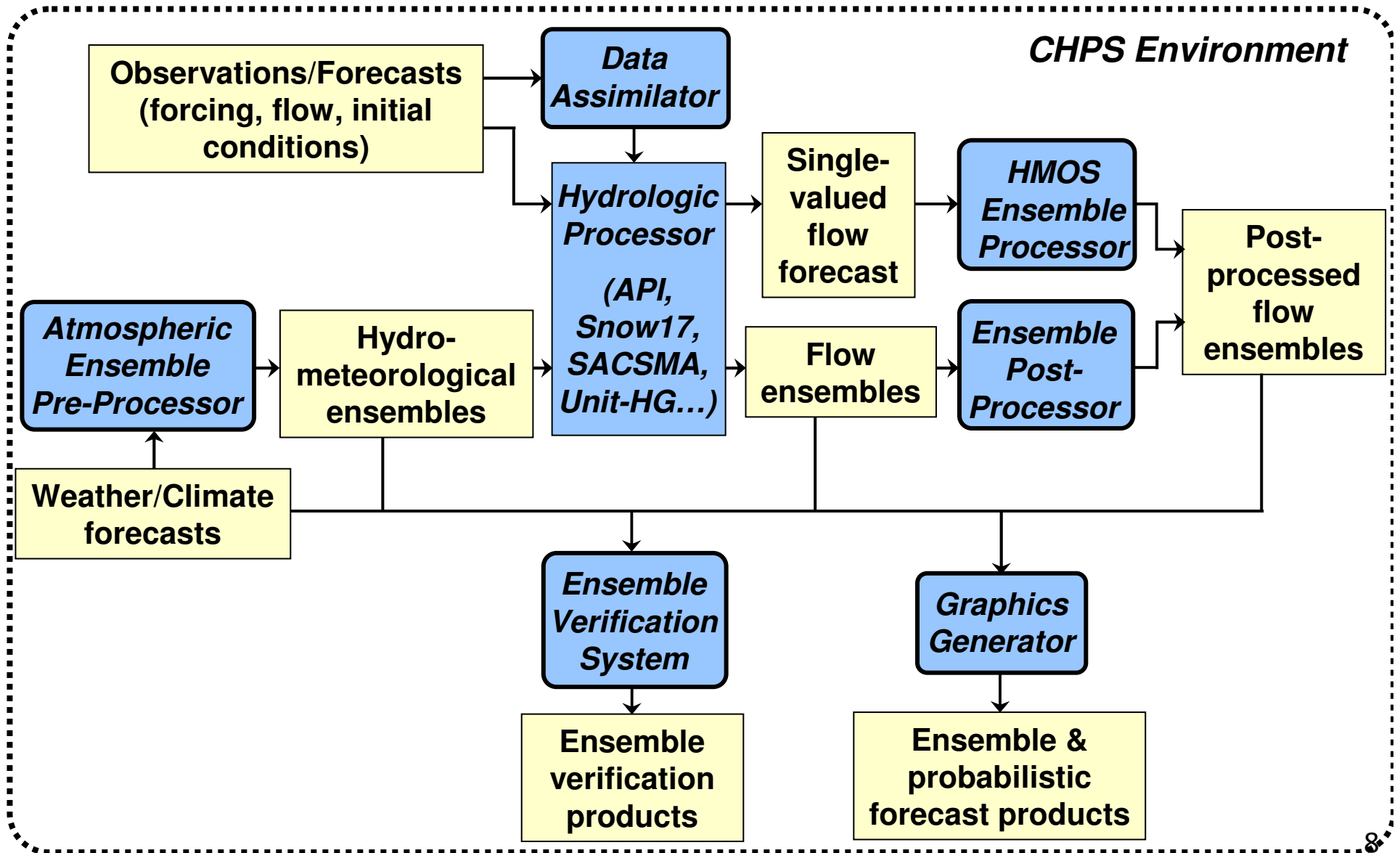


Current R&D Activities

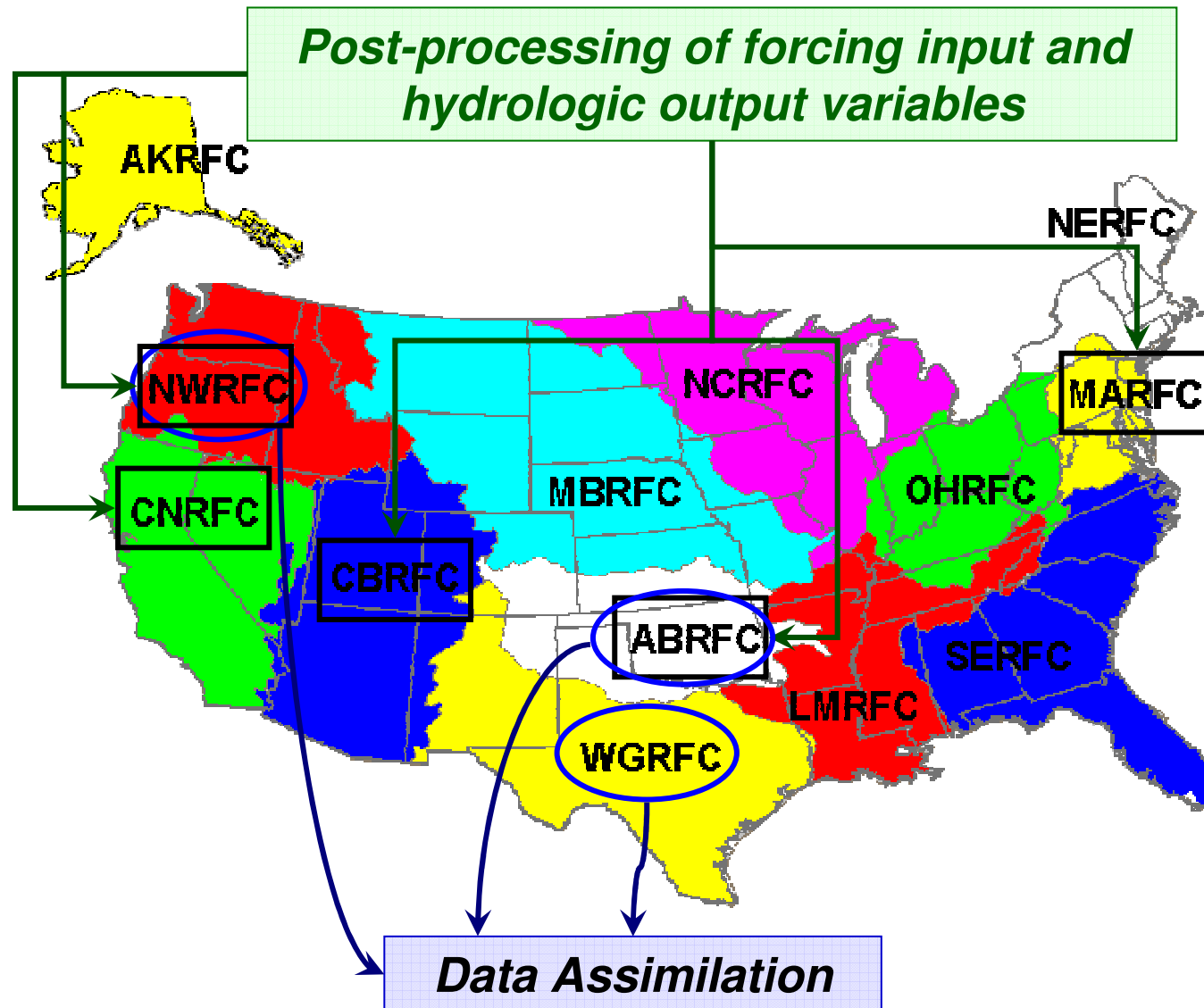
- **Integrated eXperimental Ensemble Forecast System (XEFS)** (R&D version of HEFS) interfaced with CHPS: under evaluation
- **Atmospheric Ensemble Pre-Processing** to produce forcing input ensembles at the basin scale using available weather/climate forecasts (single-valued and probabilistic) and multiple post-processing techniques
- **Hydrologic Ensemble Post-Processing** to produce hydrologic ensembles based on multiple post-processing techniques that make use of single-valued and ensemble hydrologic forecasts at the basin scale
- **Ensemble Verification** to include verification metrics and products that support model developers, RFC forecasters, and end users for diagnostic verification and real-time verification purposes
- **Data Assimilation** to generate optimal initial states and produce improved ensemble snowmelt and flow forecasts using either deterministic or ensemble data assimilation algorithms to account for uncertainty in hydrologic models (e.g., model structure, parameters, and states) and observational data (e.g., model forcing and output)

Experimental Ensemble Forecast System (XEFS)

Interfaced with Community Hydrologic Prediction System (CHPS)



Current XEFS Test Basins at NWS River Forecast Centers



Uncertainty integration in XEFS

Uncertainty in hydrologic forecast

=

Uncertainty in future forcings + **Uncertainty in everything else**

precipitation,
temperature,
potential evaporation

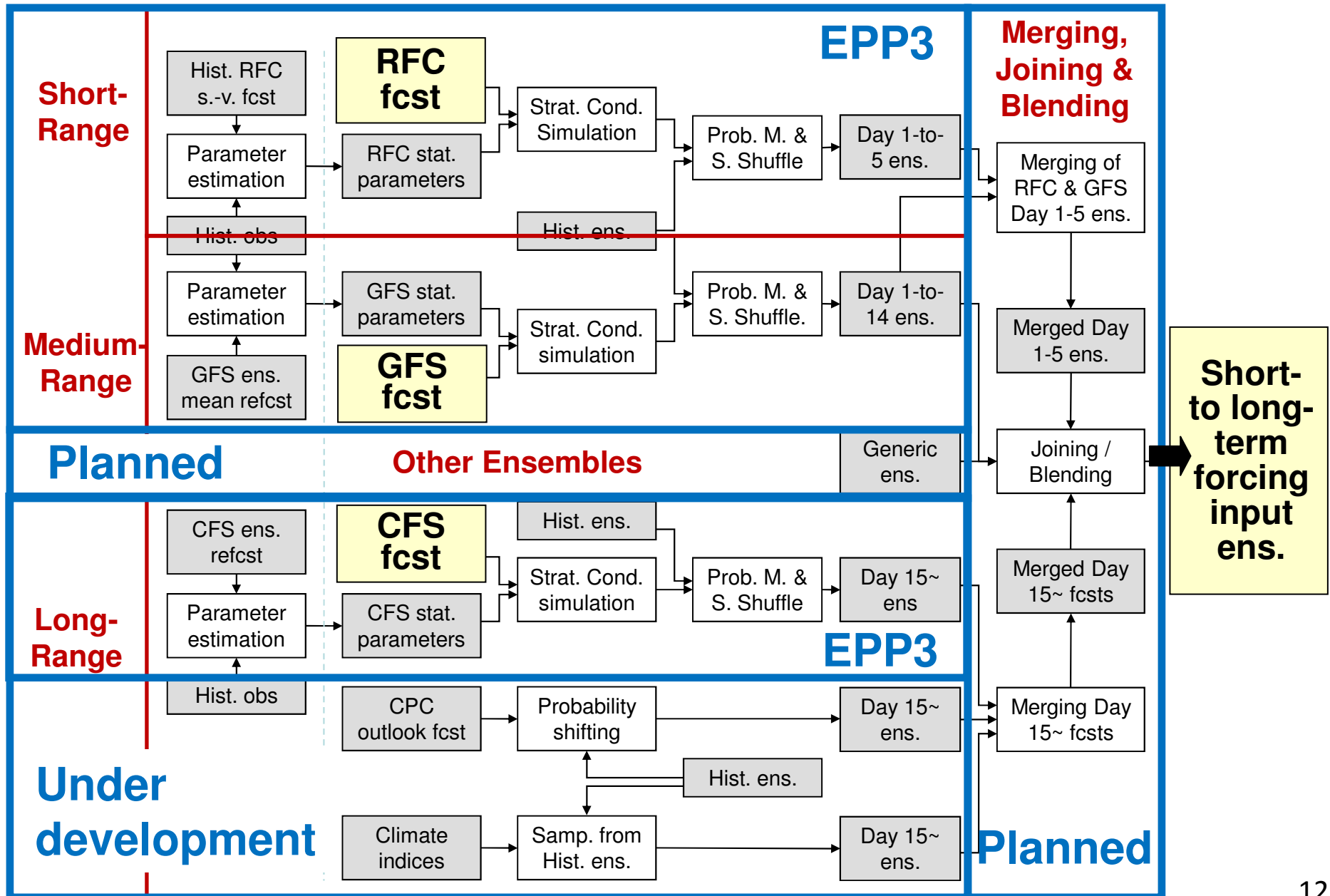
initial soil moisture conditions,
model errors,
observation errors,
etc.

- Reliable and skillful (uncertainty-integrated) hydrologic ensemble forecast requires
 - Reliable and skillful ensemble forecast of forcing variables
 - Accurate modeling and accounting of hydrologic and hydraulic uncertainties

Ensemble Pre-Processor Strategy

- Current situation
 - NWP ensembles are generally biased in the mean and spread
 - For short range, HPC/RFC forecasts are generally more accurate than NWP ensemble forecasts in some mean sense
- Initial build (EPP3)
 - Given single-valued forecast (HPC/RFC single-valued QPF, GFS ensemble mean from frozen GFS, CFS ensemble mean), statistically generate ensembles based on joint probability distribution between observed and forecast precipitation
- Future builds
 - Use new CFSv2 and GEFS datasets
 - Bring in post-processed (bias-corrected and downscaled) multi-model NWP ensembles
 - Include potential evaporation
 - Include other post-processing techniques

Envisioned Ensemble Pre-Processor



Strategy for hydrologic uncertainty modeling

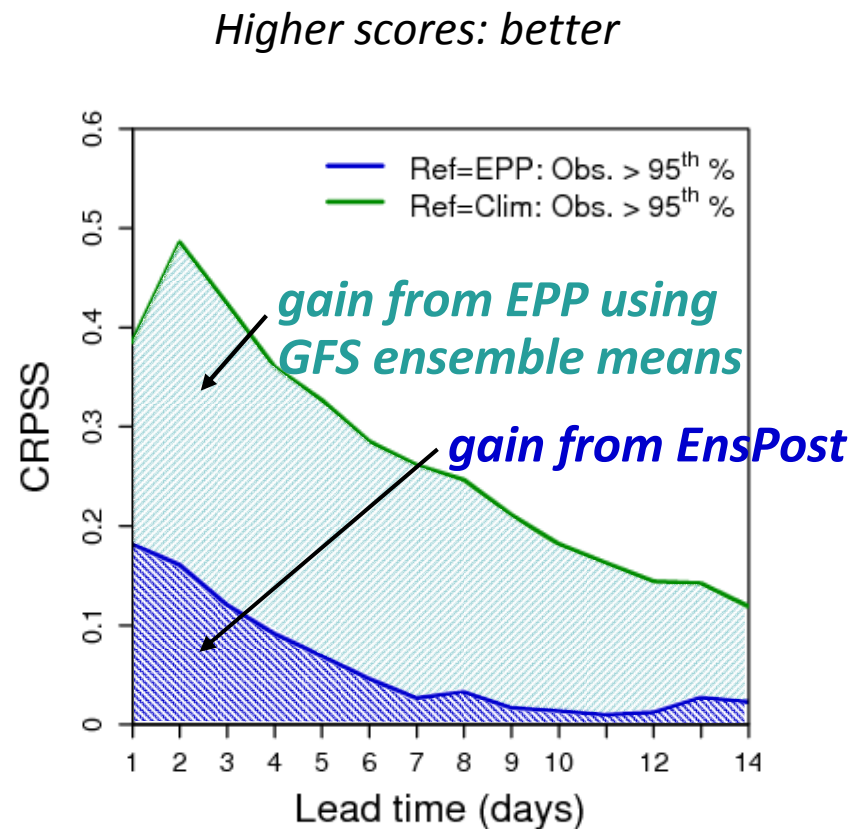
- Current approach
 - EnsPost: lump all hydrologic uncertainties into one and model it stochastically (Seo et al. 2007)
 - HMOS: model total uncertainty (input + hydrologic) in single-valued operational flow forecasts using QPF information
- Future approach
 - Include other statistical post-processing techniques
 - Uncertainty modeling of regulated flows
 - Initial condition uncertainty via ensemble data assimilation
 - Parametric uncertainty via parametric uncertainty processor
 - Multi-model ensembles for structural uncertainty

Example of verification results: XEFS flow ensembles compared to climatological ESP ensembles

Skill Score for Mean CRPS (CRPSS):

GFS-based flow generated w/ pre- and post-processing compared to

- GFS-based flow w/o post-processing
- climatology-based flows (operational ESP) (w/o pre- and post-processing)
- Very large improvement w/ pre-processing and GFS ens. means over climatological ESP
- Significant improvement w/ post-processing



Strategy for data assimilation

- Current approach:
 - develop DA tools with single-valued forecasts and extend to ensemble DA
 - interface them into OpenDA for CHPS application
- Techniques currently tested
 - Hydrologic routing DA (1DVAR) to assimilate streamflow into 3-parameter Muskingum routing model
 - 2DVAR to assimilate streamflow, precipitation and PE for Sacramento and Unit Hydrograph models (implemented)
 - Snow and streamflow DA (including different techniques, e.g., Ensemble Kalman Filter and Maximum Likelihood Ensemble Filter)
 - 4DVAR to assimilate streamflow, soil moisture, precipitation and PE for gridded SAC and kinematic-wave routing in Research Distributed Hydrologic Model (RDHM)

Ensemble Verification System

- Currently Available Features
 - Java tool with structured GUI
 - Only verifies numerical time-series for individual points/areas
 - Supports flexible conditional verification
 - Computes several key metrics (deterministic and ensemble) for reliability, resolution, discrimination, skill
- Status
 - EVS version 3.0 released in October 2010
www.nws.noaa.gov/oh/evs.html
 - Enhancements underway (e.g., estimation of confidence intervals)
 - Fully documented and freely available

Operational hydrologic ensemble forecasting

Challenges

- Appropriately model and integrate uncertainties introduced from data, model, and human sources
- Combine ensemble forcing for short, medium, and long ranges from multiple sources
- Maintain spatio-temporal relationships across different scales
- Include forecaster skill in short-term inputs (QPF, temperature, etc.)
- Include forecaster guidance of hydrologic model operation
- Maintain coherence between deterministic and ensemble forecasts
- Provide uncertainty information in a form and context that is easily understandable and useful to the customers
- Reduce the cone of uncertainty for effective decision support
 - Improve accuracy of meteorological and hydrologic models
- Improve uncertainty modeling and observations of rare and extreme events (e.g. record flooding, drought without any historical analog)
- Greatly improve computing, database and data storage capabilities

OHD-NCEP Collaborations

- Common areas of expertise
 - Bias correction, statistical downscaling, data assimilation, ensemble verification
 - Inter-comparison of different techniques and verification results
- Coordination on new forecasting systems
 - Hindcast strategy, dataset sharing (reforecasts, forecasts, and analyses), ensemble verification
 - Hydrology requirement: long-term reforecast datasets required for calibration at RFC basin scale

Thank you!

HEP Group Website

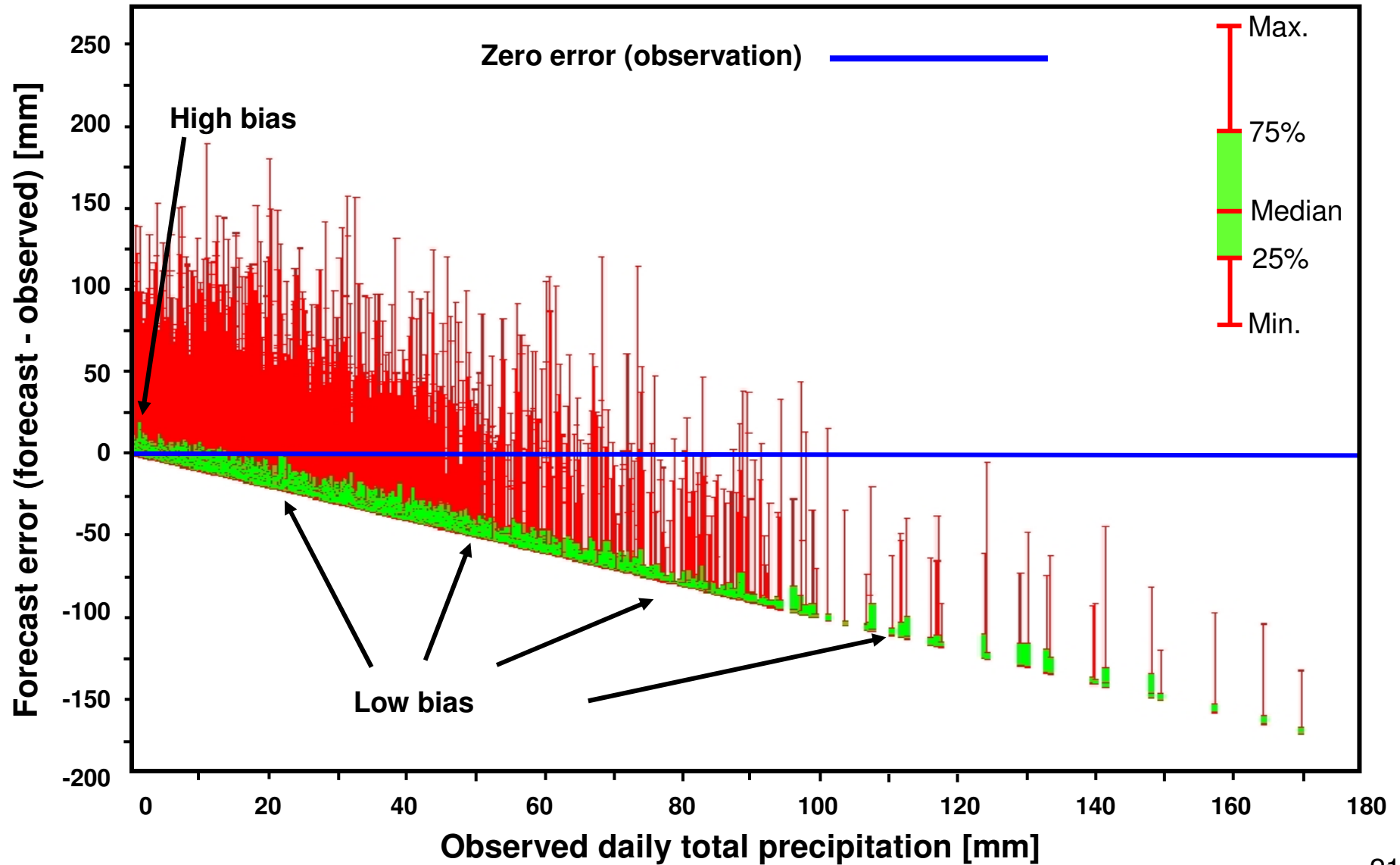
http://www.weather.gov/oh/hrl/hsmb/hydrologic_ensembles/index.html

XEFS Website

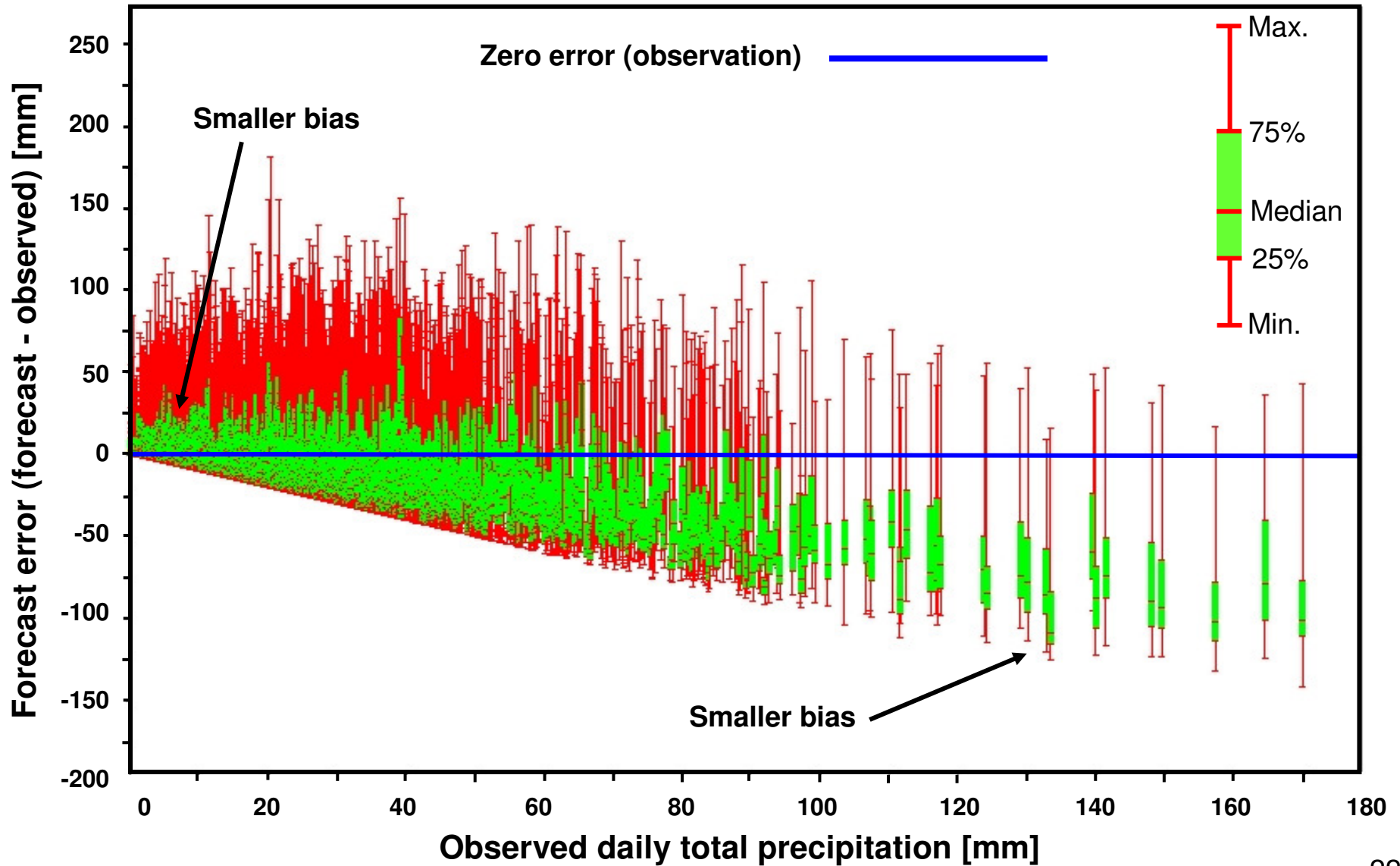
<http://www.weather.gov/oh/XEFS/>

Extra Slides

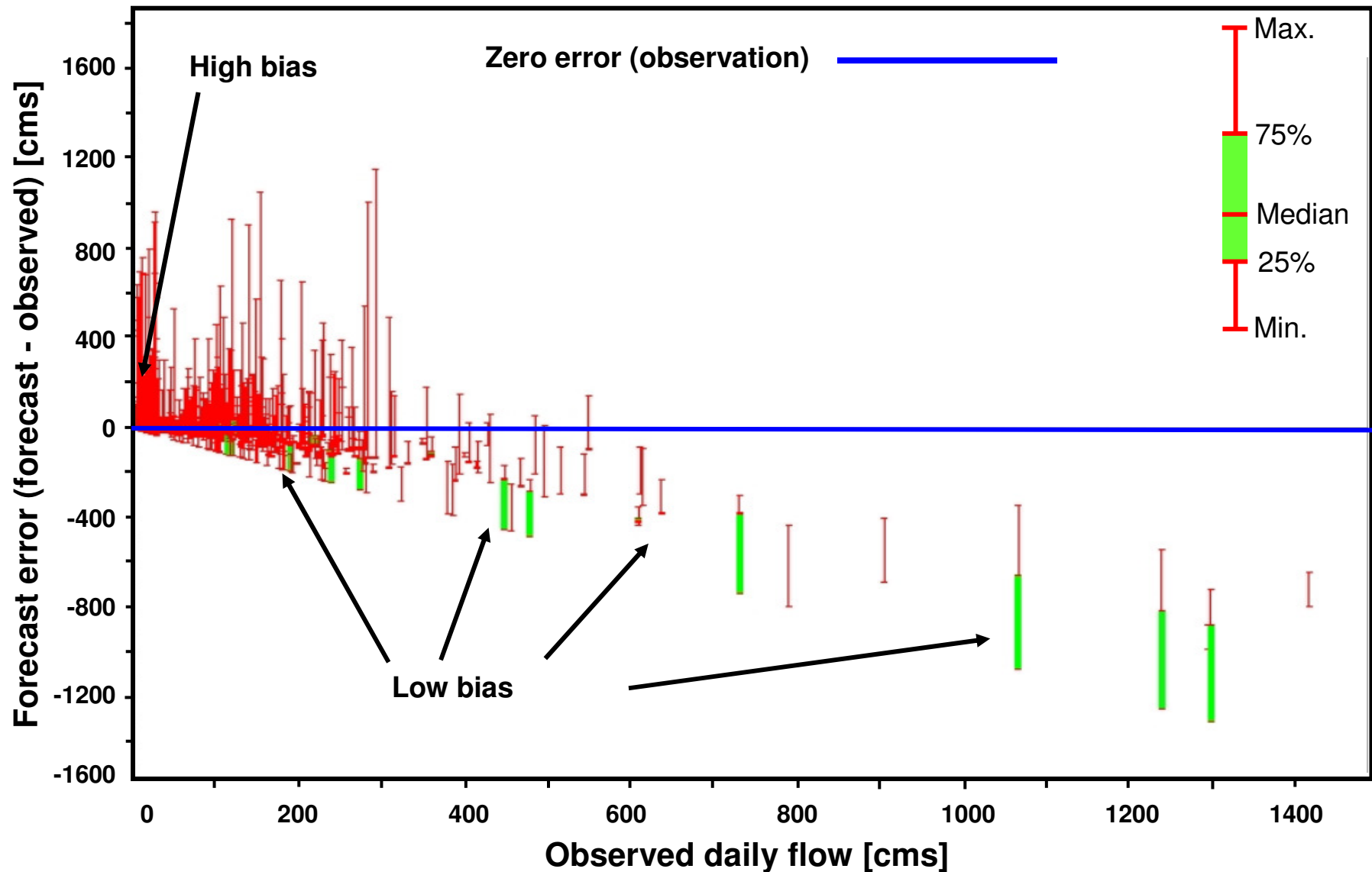
Example: Errors in Climatological Precipitation Forecast (Day 1)



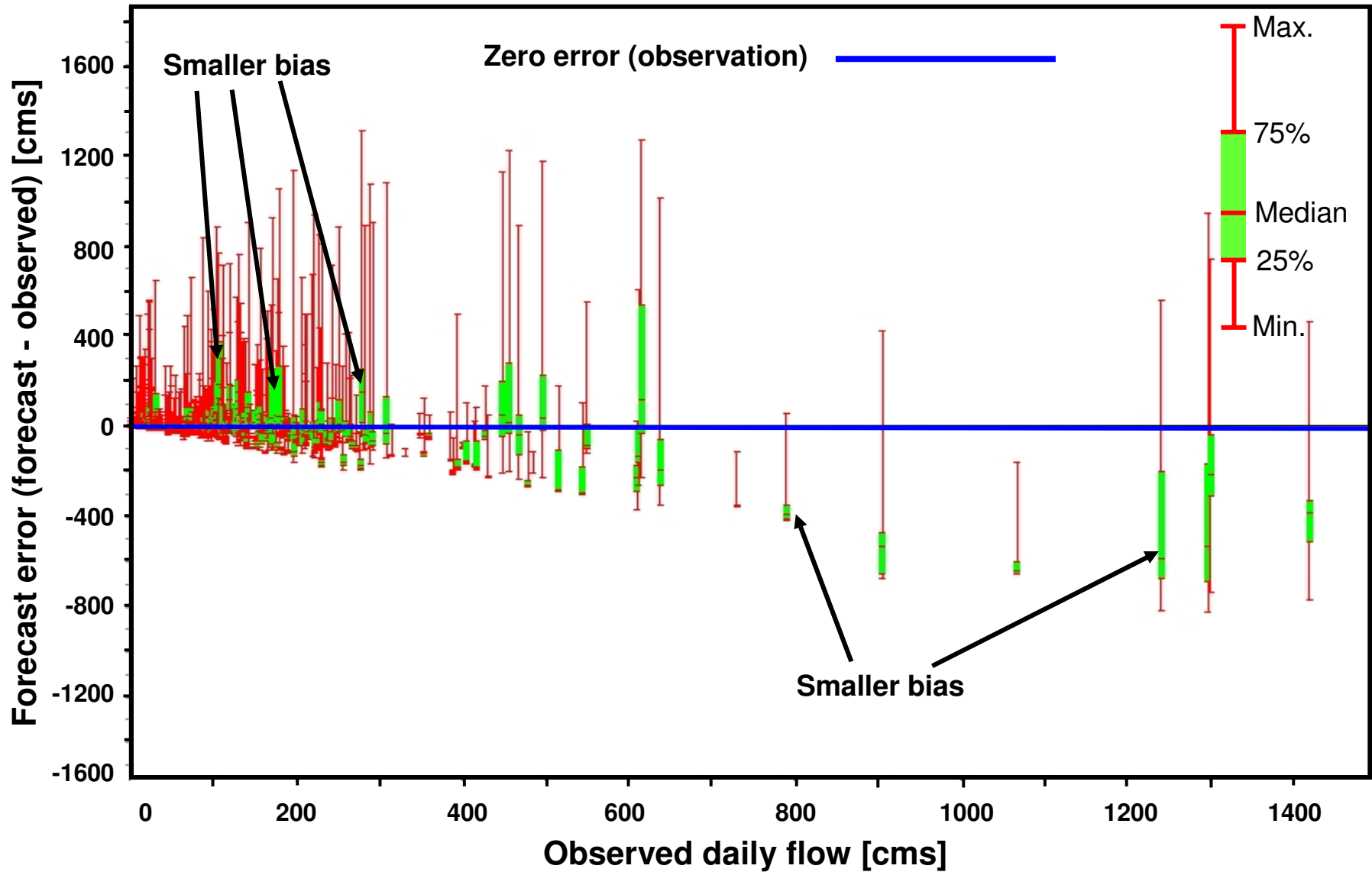
Example: Errors in GFS-based EPP Precipitation Forecast (Day 1)



Example: Errors in Climatology-based Flow Forecast (Day 1)



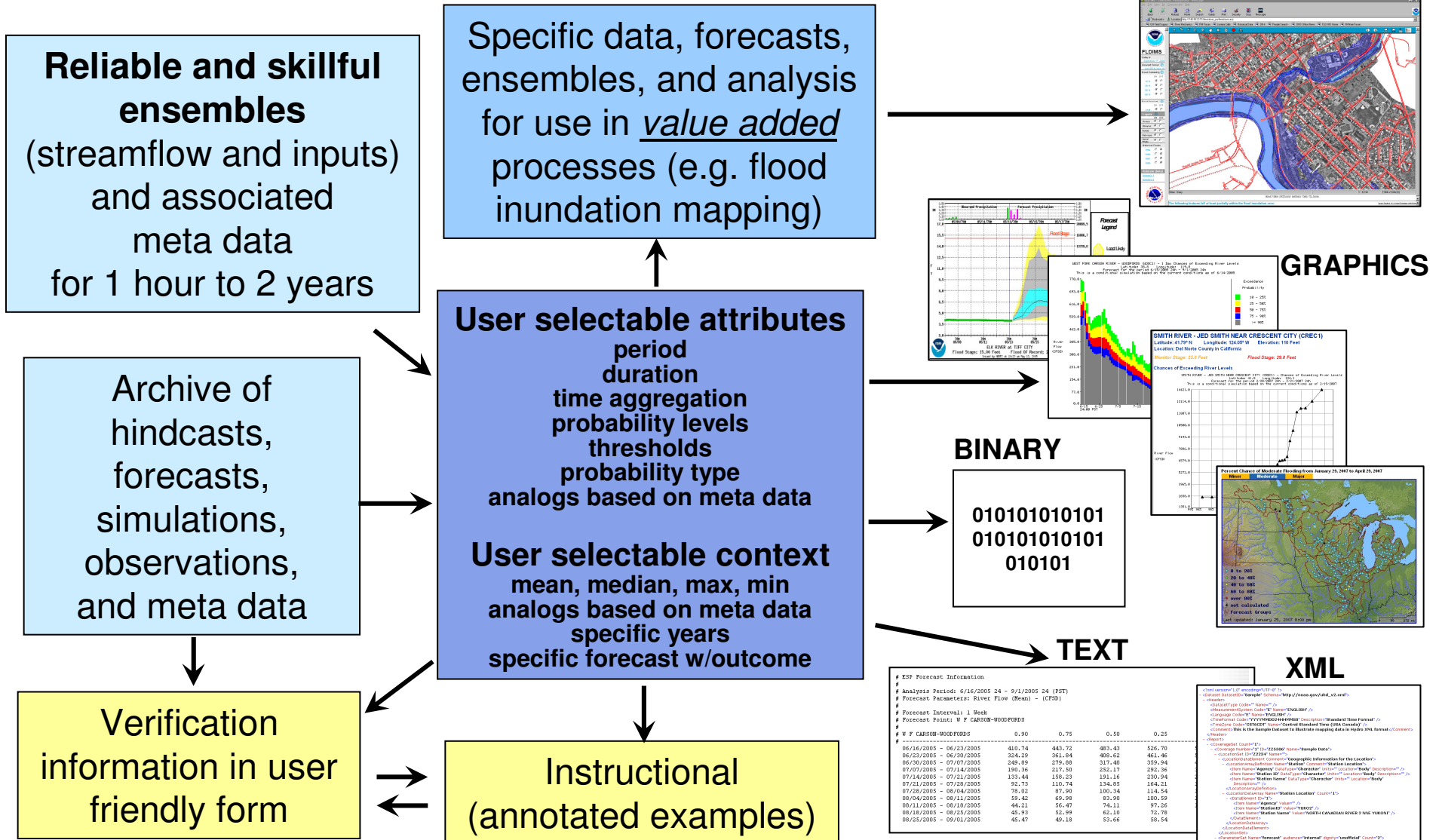
Example: Errors in GFS-based EPP-EnsPost Flow Forecast (Day 1)



Graphic Generator

- Current build
 - Basic ESPADP functionality for CHPS
 - Incorporated enhanced functionality from RFC feedback
 - Tested in operating client environment
- On-going – move to operations
 - On-demand product sharing across operating clients
 - ESPADP-like default template products
 - Ability to apply a product/template to all forecast points
 - Coordinating ESPADP differences with AHPS
 - Training Manual & webinar (funded by NSTEP)

Envisioned XEFS Products



Uncertainty integration strategy in XEFS

$$f_1(q_f | q_o) = \int f_2(q_f | q_o, s_f) f_3(s_f | q_o) ds_f$$

**Predictive
uncertainty in
streamflow**

**Residual hydrologic
uncertainty**

**Uncertainty in
model-predicted
streamflow**

where q_f Streamflow at some future times
 q_o Observed flow up to and including the current time
 s_f Model-predicted streamflow at the future times

Krzysztofowicz (1999)

$$f_3(s_f | q_o) = \iiint f_4(s_f | b_f, i, p, q_o) f_5(b_f | i, p, q_o) f_6(p | i, q_o) f_7(i | q_o) db_f di dp$$

**Uncertainty in
model-predicted
streamflow**

**Conditional hydrologic
model simulation**

**Future forcing
uncertainty**

**Parametric
uncertainty**

**Initial condition
uncertainty**

where b_f Future boundary conditions (precipitation, temperature)
 i Initial conditions
 p Model parameters

Seo et al. (2006)

Uncertainty integration strategy in XEFS

w/o data assimilator and parametric uncertainty processor

$$f_1(q_f | q_o) = \int f_2(q_f | q_o, s_f) f_3(s_f | q_o) ds_f$$

Predictive uncertainty in streamflow **Residual hydrologic uncertainty** **Uncertainty in model-predicted streamflow**

where q_f Streamflow at some future times
 q_o Observed flow up to and including the current time
 s_f Model-predicted streamflow at the future times

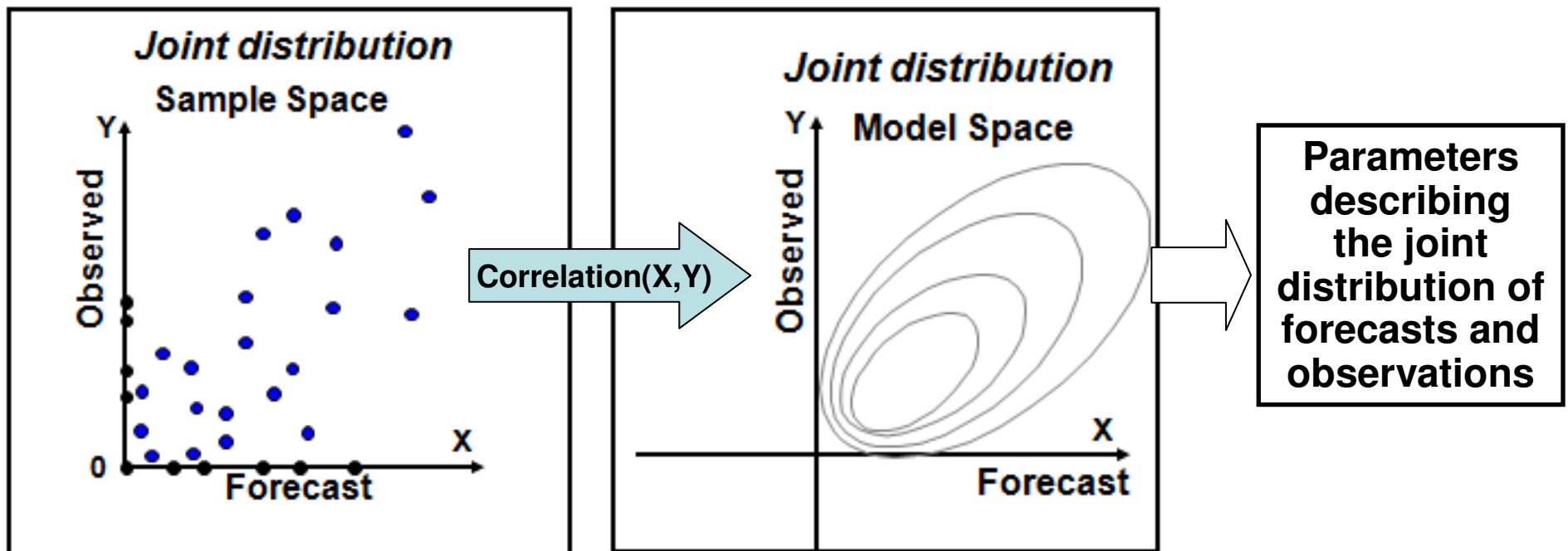
$$f_3(s_f | q_o) = \int f_4(s_f | b_f) f_5(b_f) db_f$$

Uncertainty in model-predicted streamflow **Conditional hydrologic model simulation** **Future forcing uncertainty**

where b_f Future boundary conditions (precipitation, temperature)

EPP Calibration Processor

Off line, model joint distribution between single-valued QPF and verifying observation for each lead time (same process used for temperature but with different distributions)

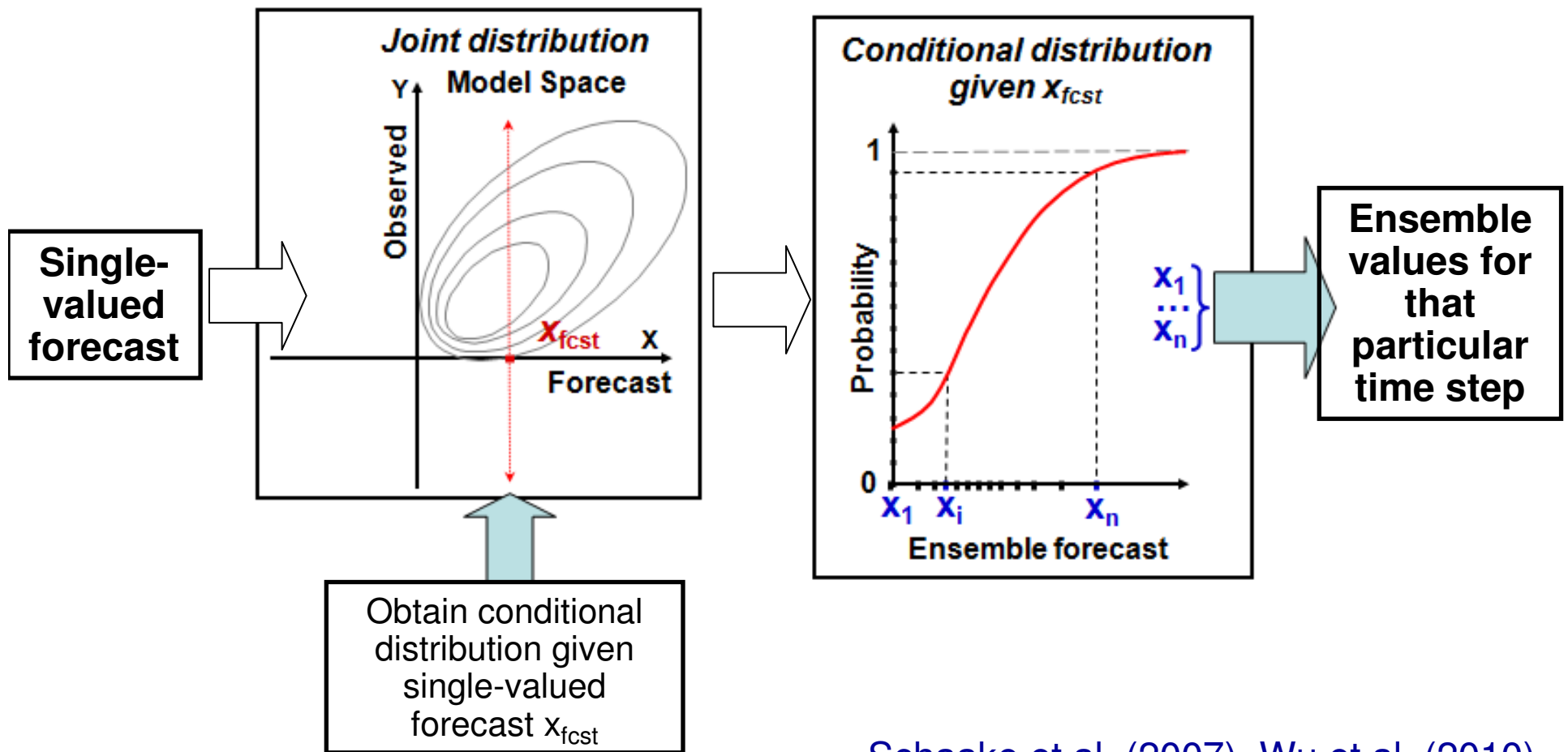


Multi-year archive of single-valued QPF necessary

Schaake et al. (2007), Wu et al. (2010)

EPP Real-Time Processor: Step 1

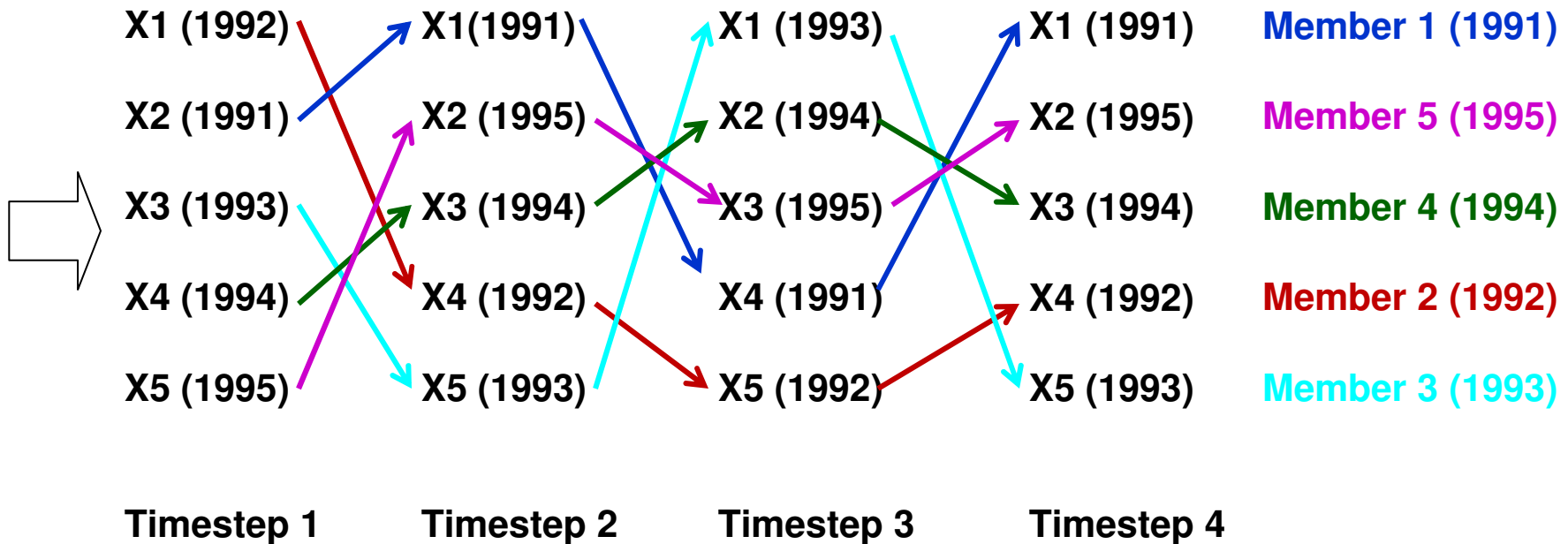
In real-time, given single-valued QPF, generate ensemble traces from the conditional distribution for each lead time



Schaake et al. (2007), Wu et al. (2010)

EPP Real-Time Processor: Step 2

In real-time, string together lead-time specific ensemble values across lead times to generate traces

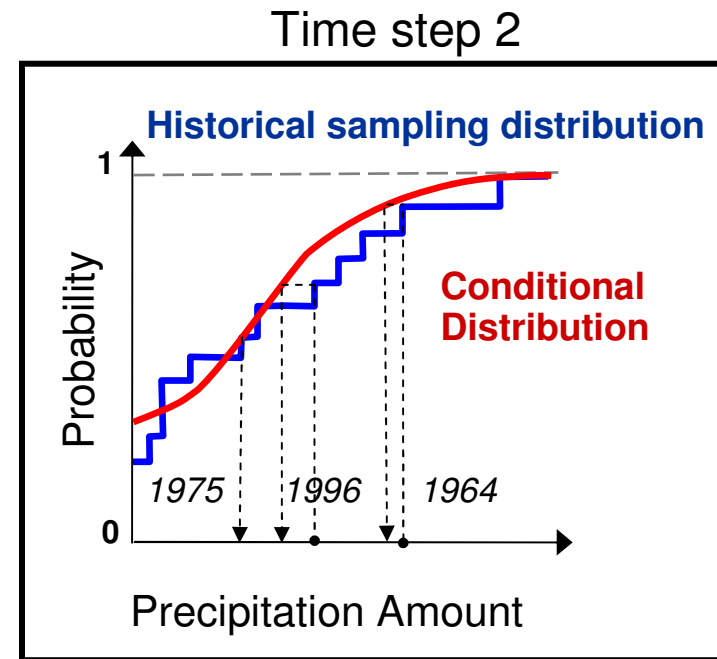
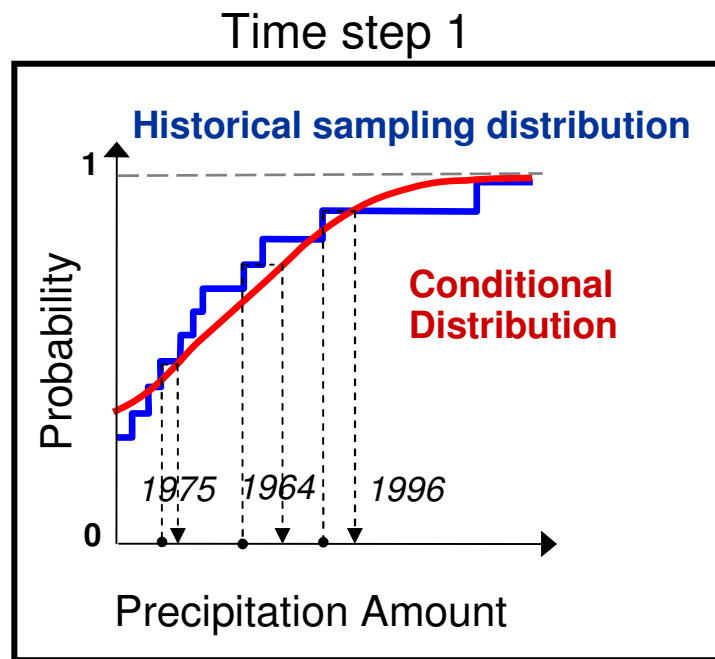


Schaake Shuffle (Clark et al. 2004)

EPP Real-Time Processor: Step 2

In real-time, string together lead-time specific ensemble values across lead times to generate traces

For each time step of the forecast period, arrange precip/temp ensemble members such that they have the same ordering as historical observations



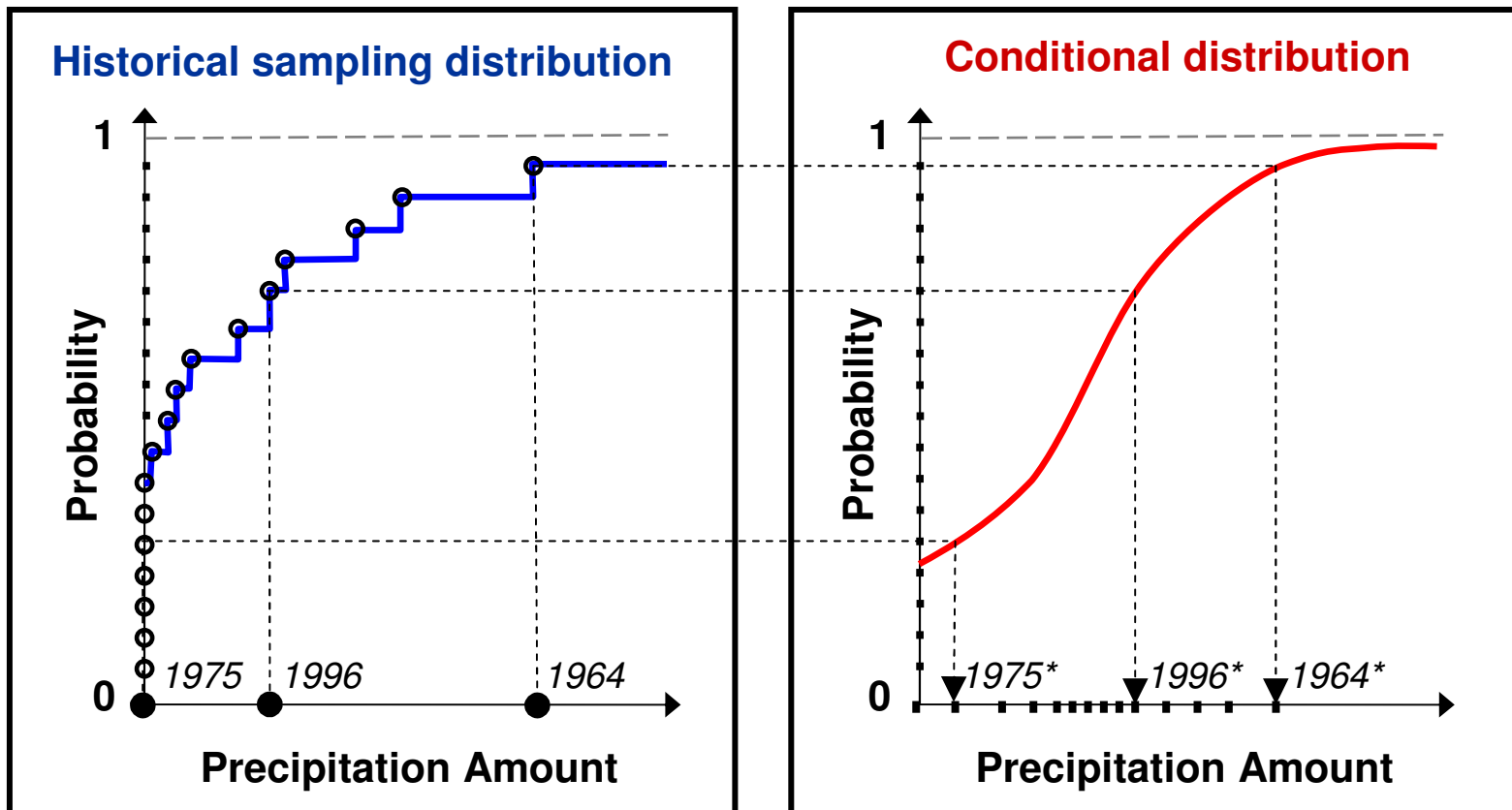
Different illustration of Schaake Shuffle (Clark et al. 2004)

EPP Real-Time Processor: Step 2

In real-time, string together lead-time specific ensemble values across lead times to generate traces

Stratified sampling: $n+1$ intervals of probability to define n ensemble values

Schaake Shuffle: re-order ensemble values based on historical observations



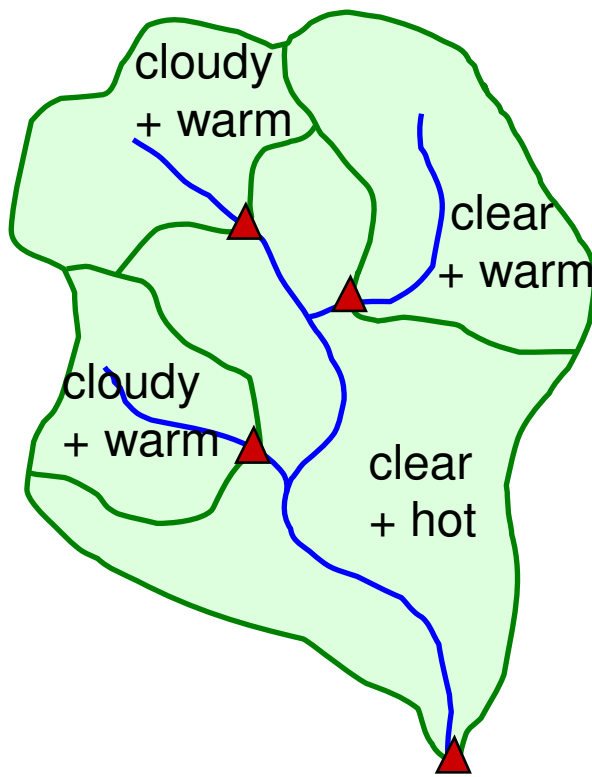
Different illustration of Schaake Shuffle (Clark et al. 2004)

Ensemble Preprocessor: Schaake Shuffle

Climatology used to identify properties of precipitation and temperature in space and time

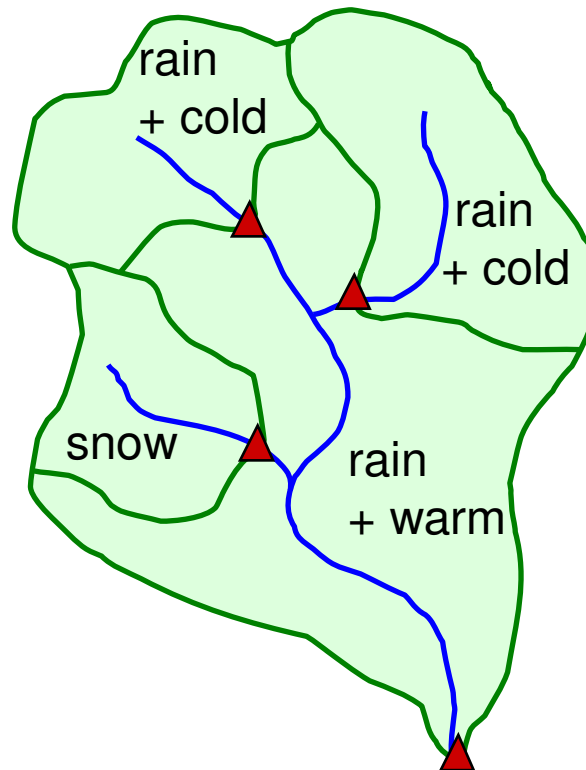
Example of historical events for a given date

1975: clear + hot



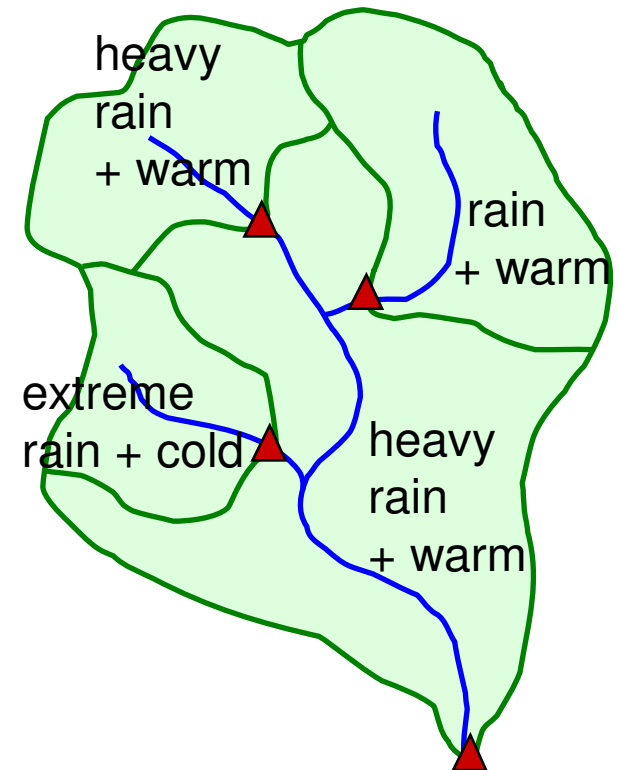
Low flow

1996: rain + cold



Medium flow

1964: very heavy rain + warm



High flow

Ensemble Preprocessor: Schaake Shuffle

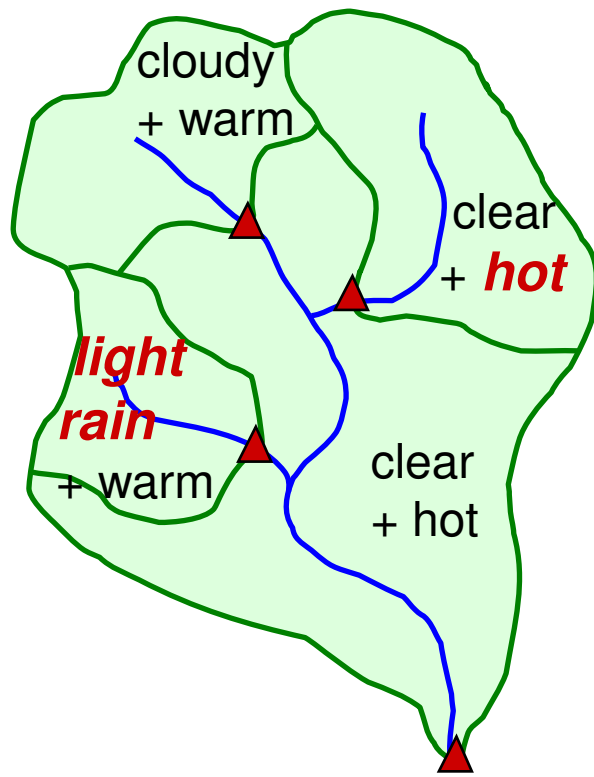
Conditional forecast ensembles constructed to maintain properties of precipitation and temperature in space and time

Example of ensemble forecasts for a given date

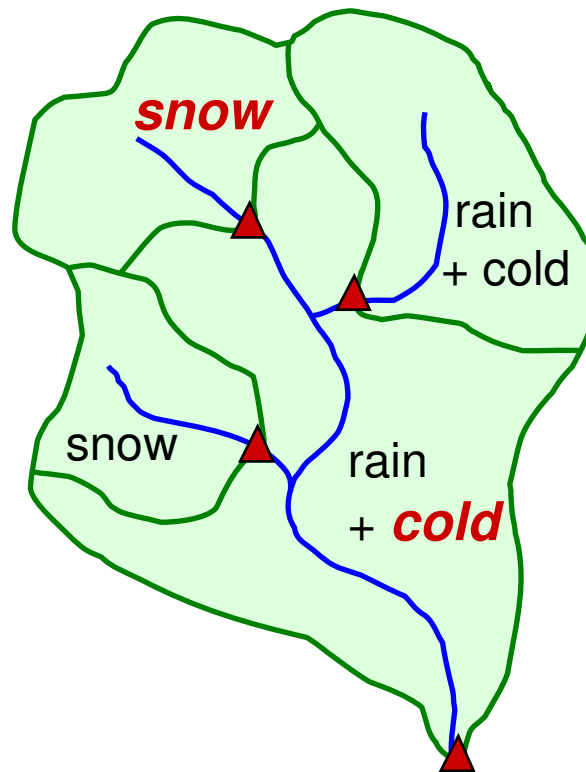
1975*: mostly clear + hot

1996*: snow/rain + cold

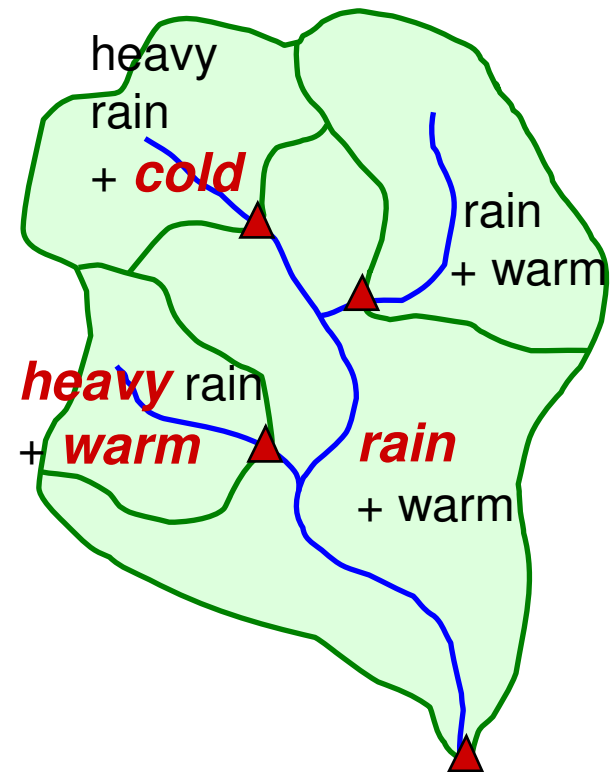
1964*: heavy rain + warm



Low flow



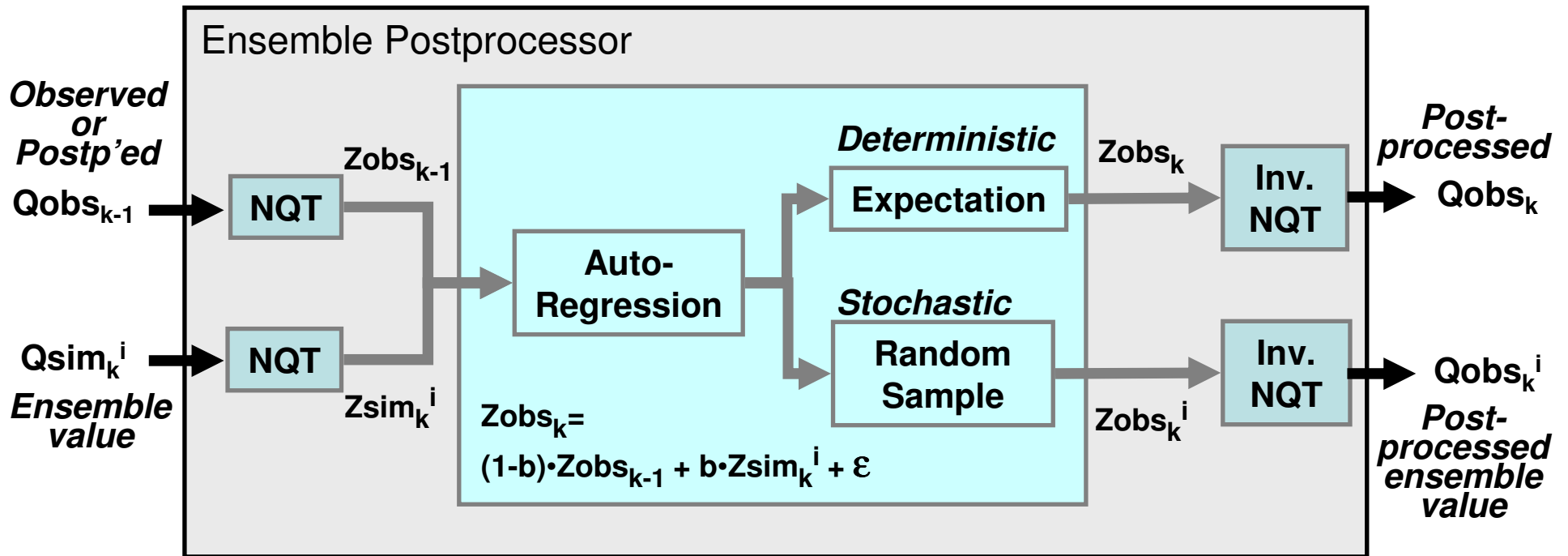
Medium flow



High flow

Ensemble Postprocessor: Methodology

- Process for lead day k for the i^{th} ensemble member



Observed or simulated value ingested by Ensemble Postprocessor:

Lead day $k = 1$: Q_{obs_0} current observation

Lead day $k > 1$: $Q_{obs_{k-1}} / Q_{obs_{k-1}^i}$ previously postprocessed value

Ensemble Postprocessor: Future Research

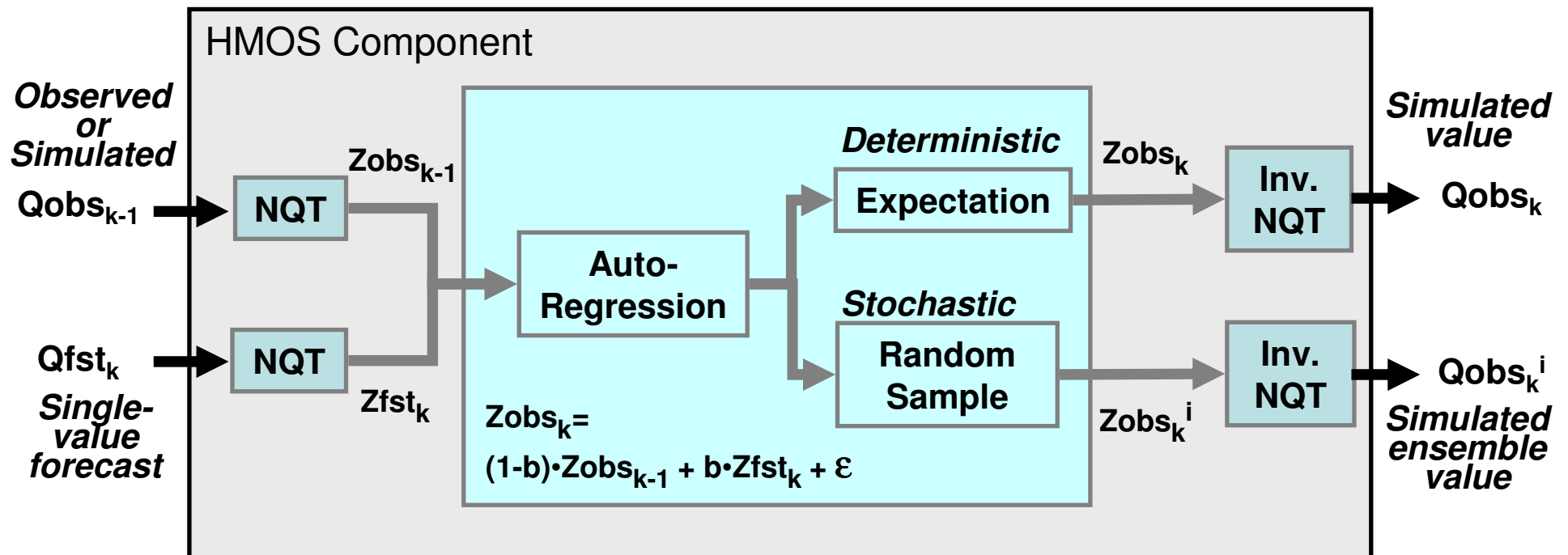
- Disaggregating technique to generate 6-hr ensembles
- Performance of the ensemble postprocessor is sensitive to data availability
- If long-duration data is available, the postprocessor performs as expected (correct model biases, produce reliable ensemble traces)
- Ensemble postprocessor does not handle regulated flows very well
- Storm typing/stratification/conditioning is necessary to handle disparate events (e.g. rain-on-snow)
- Perturbation and hybrid approaches should also be considered to deal with data paucity and to capture longer-memory model dynamics better

Hydrologic Model Output Statistics (HMOS)

- HMOS Approach:
 - Accounts for total uncertainty via establishing statistical relationships between single-valued forecasts and observed flows, using QPF info
- Current prototype:
 - Simpler approach for short-term flow ensemble generator
 - Combination of Model Output Statistics (MOS) and statistical adjust-Q technique
 - Statistical relationships between forecast and observed flow for each forecast lead time (ensembles generated at 6-hr time step) based on flow stratification (multiple categories defined from bias-adjusted flow forecast and accumulated QPF amount)
 - Uses forecast flows, recent observed flows, and QPF info
 - Needs long records of model stage/forecast flows, stage/forecast observations, and QPF

HMOS: Methodology

- Process for lead time k to generate the i^{th} ensemble member from single-value forecast: similar to Ensemble Postprocessor



Observed or simulated value ingested by HMOS:

Lead time $k = 1$: **Q_{obs_0}** current observation

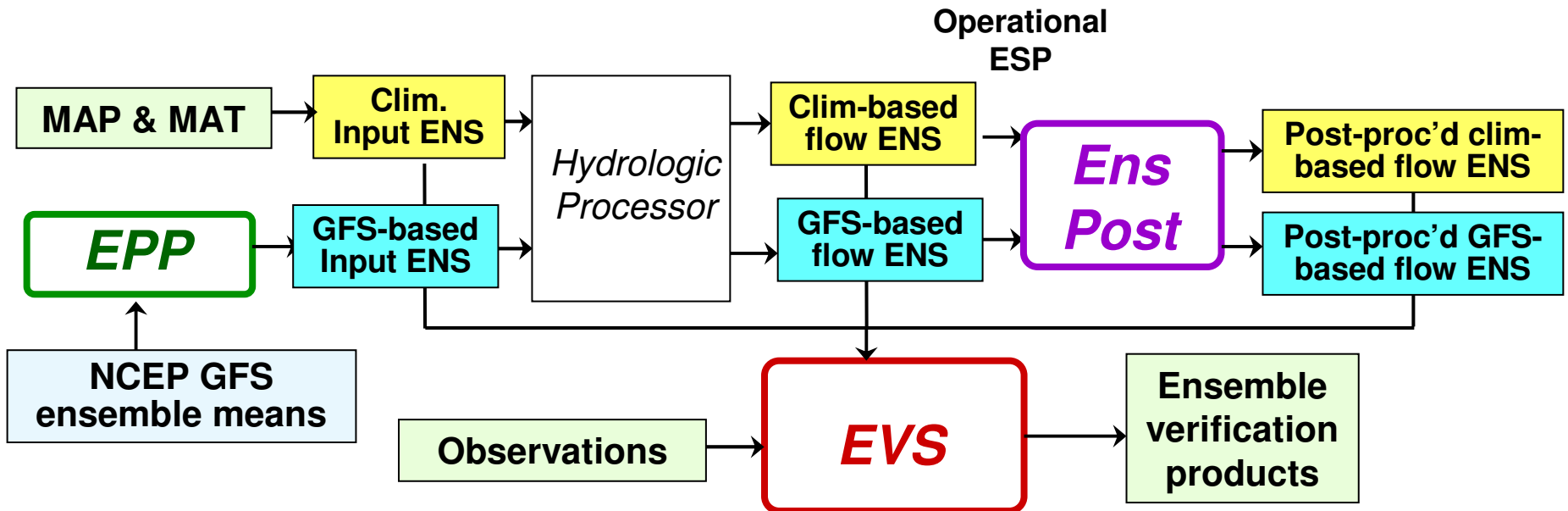
Lead time $k > 1$: **$Q_{obs_{k-1}}$ / $Q_{obs_{k-1}}^i$** previously simulated value

Case Study

- North Fork of the American River (875 km²) near Sacramento, California
- Daily products, 14 lead days, 45 members, 1979-2005
- GFS-based **Ens. Pre-Processor (EPP)** and **Ens. Post-Processor (EnsPost)** against climatology, evaluated via **Ensemble Verification System (EVS)**

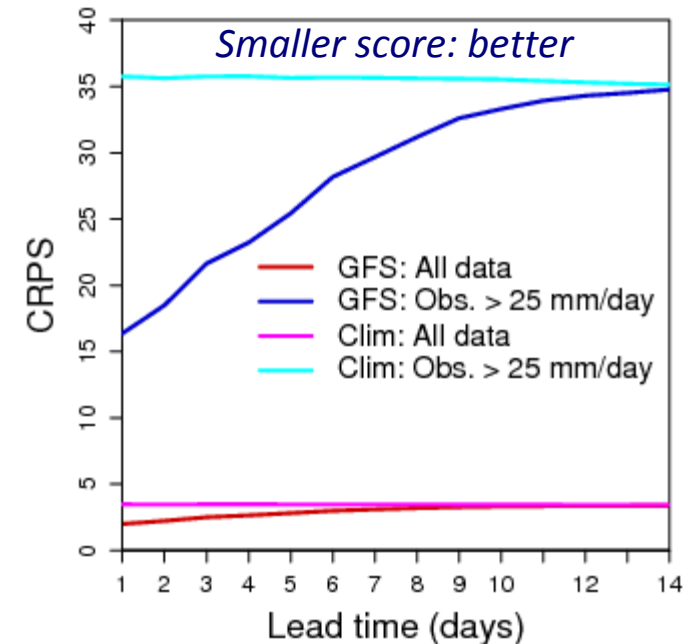
EPP: retain skill in single-valued input fcst & generate unbiased ENS

EnsPost: account for all hydrologic uncertainties

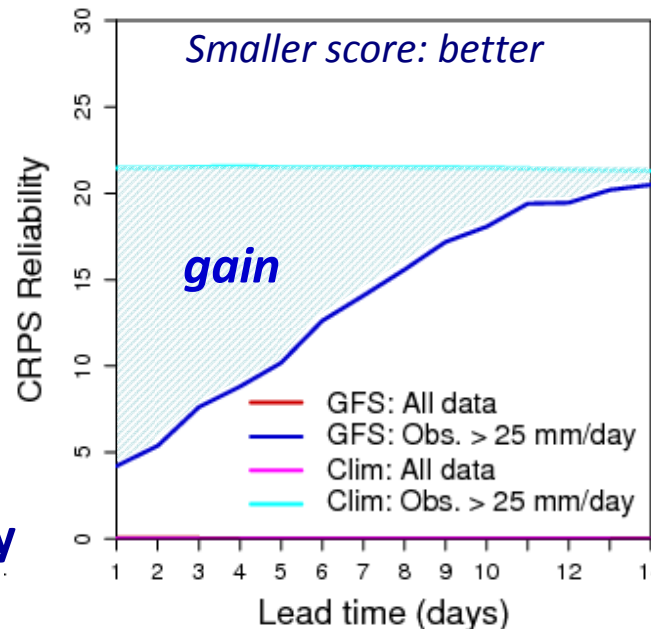


Verification Results: Pre-Processor

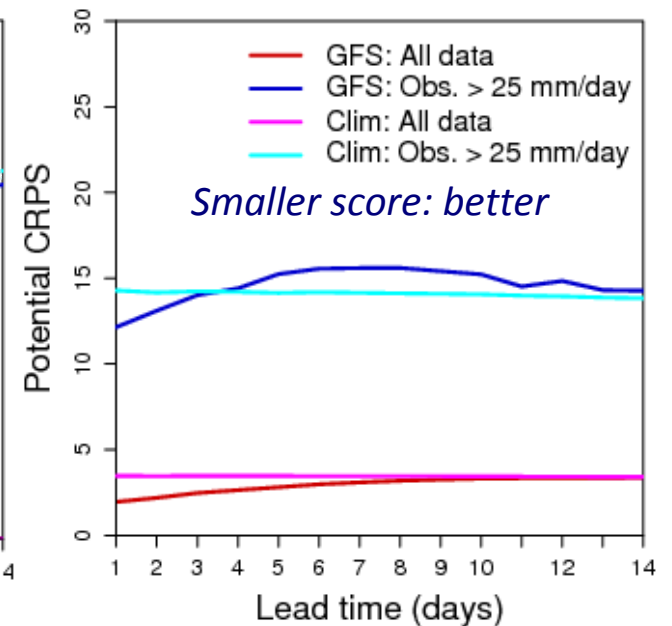
- GFS-based 24-hr **precipitation ENS** from EPP vs. Climatology:
 - Mean Continuous Ranked Probability Score (CRPS)
 - Mean CRPS decomposition



Mean CRPS= Reliability
+ Potential CRPS

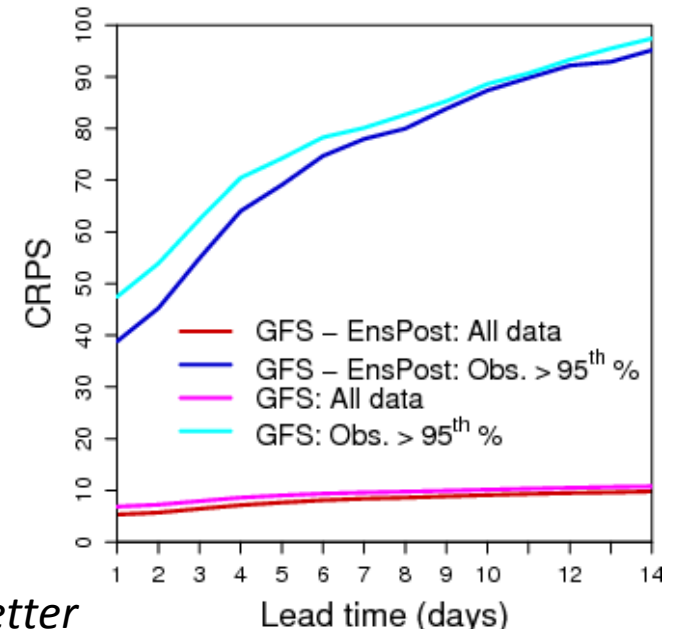


Gain is mostly in reliability



Verification Results: Post-Processor

- 24-hr **flow ENS** from EPP GFS-based forcing w/ vs. w/o EnsPost
 - **Mean CRPS:** improvement from EnsPost is most significant at short lead time, from reducing uncertainty in initial conditions

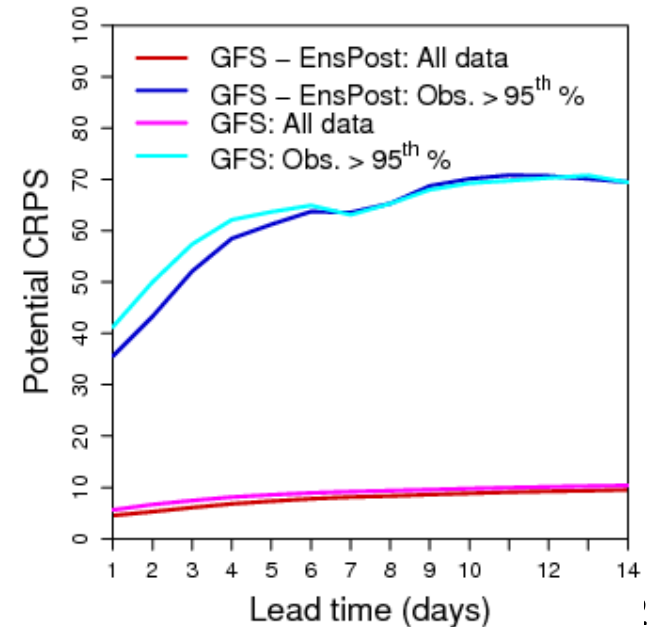
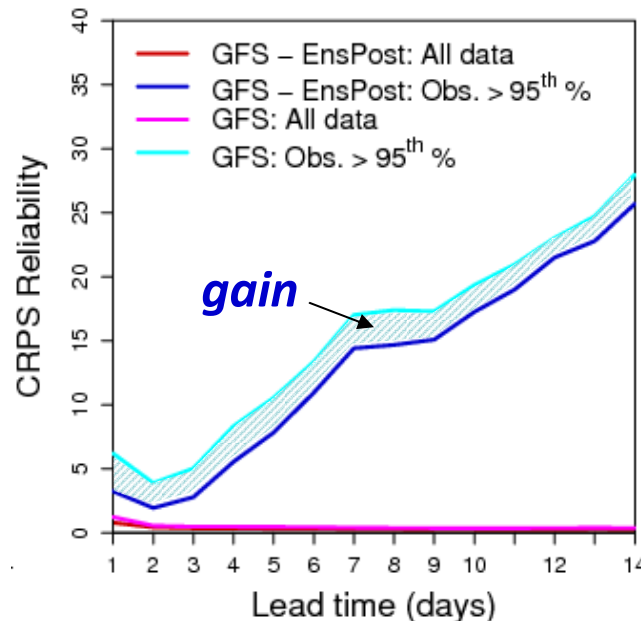


- **Mean CRPS decomposition**

Mean CRPS =
Reliability
+ Potential CRPS

Significant gain in reliability w/ EnsPost at all lead times

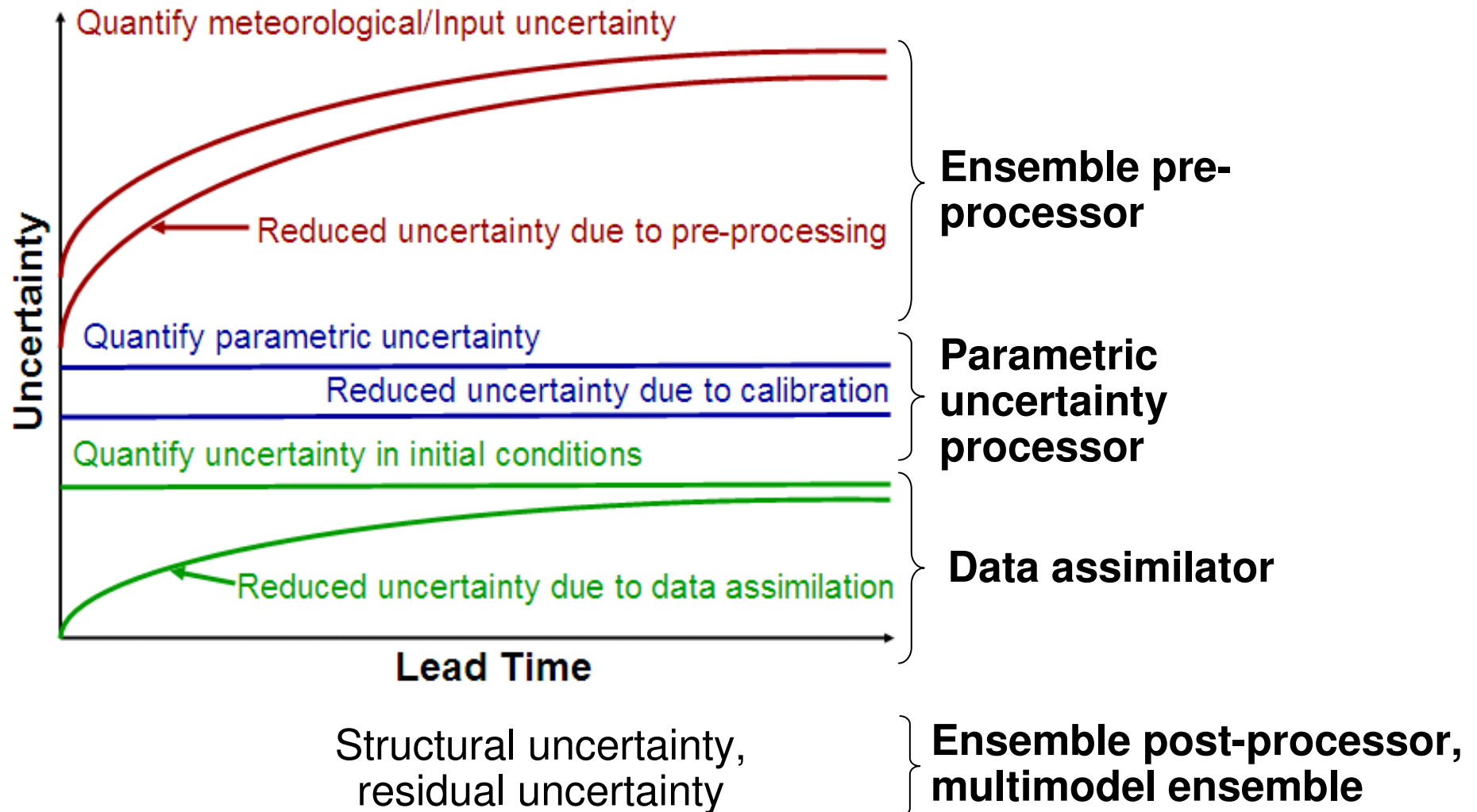
Smaller scores: better



Why ensemble forecasting?

- Provide estimate of forecast uncertainty
 - Forecasters get objective guidance for level of confidence in forecasts
 - End users decide whether to take action based on their risk tolerance
- Help extend forecast lead time or ascertain its limit
 - Weather and climate forecasts are highly uncertain and noisy; they cannot practically be conveyed as single-valued
- Improve forecast accuracy
 - Averaging two good (or bad) forecasts in some way is usually better than either of the two
- Help improve forecast quality cost-effectively
 - Assessment of relative importance of major sources of uncertainty helps define targeted improvements

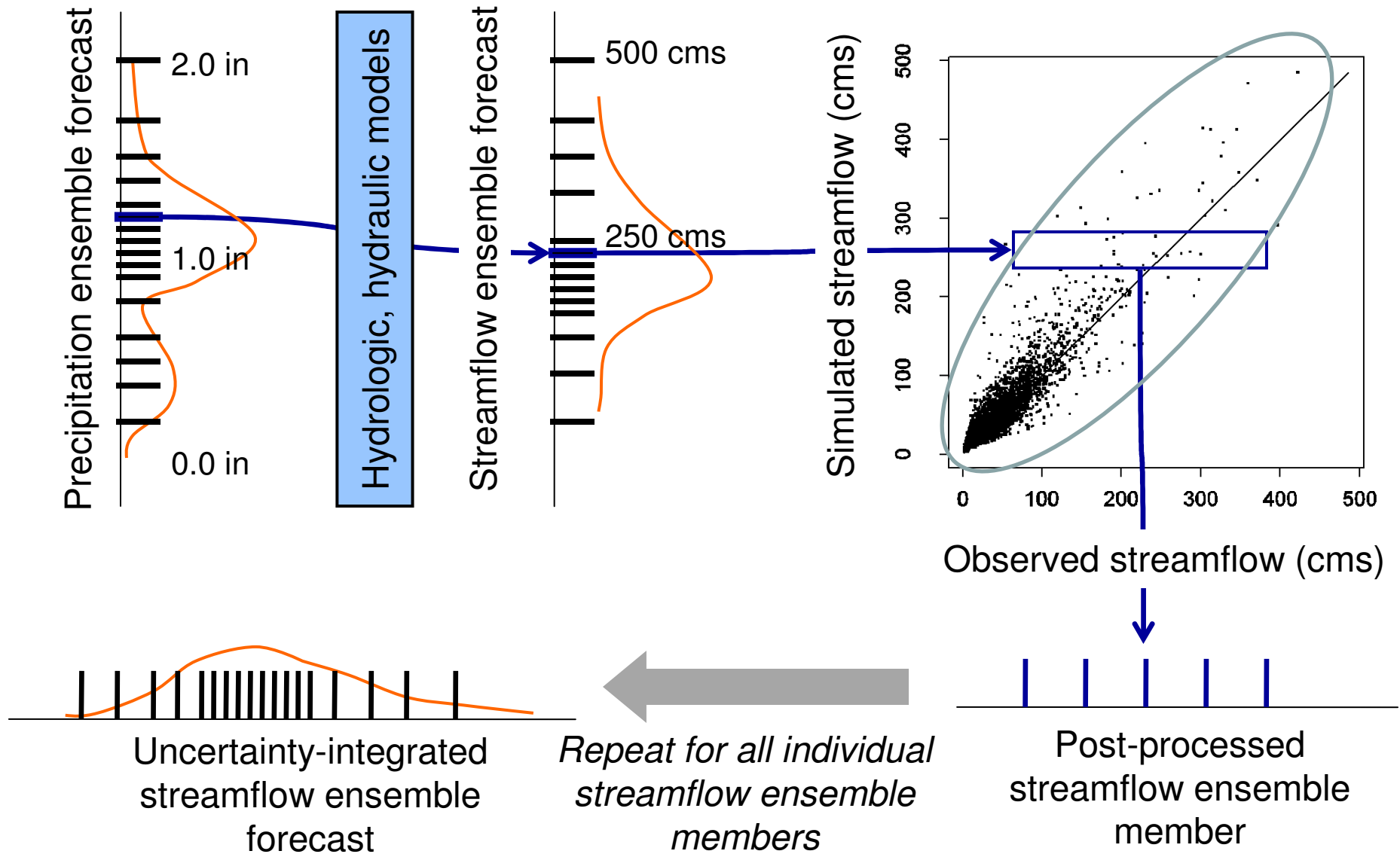
Uncertainties in hydrologic forecast

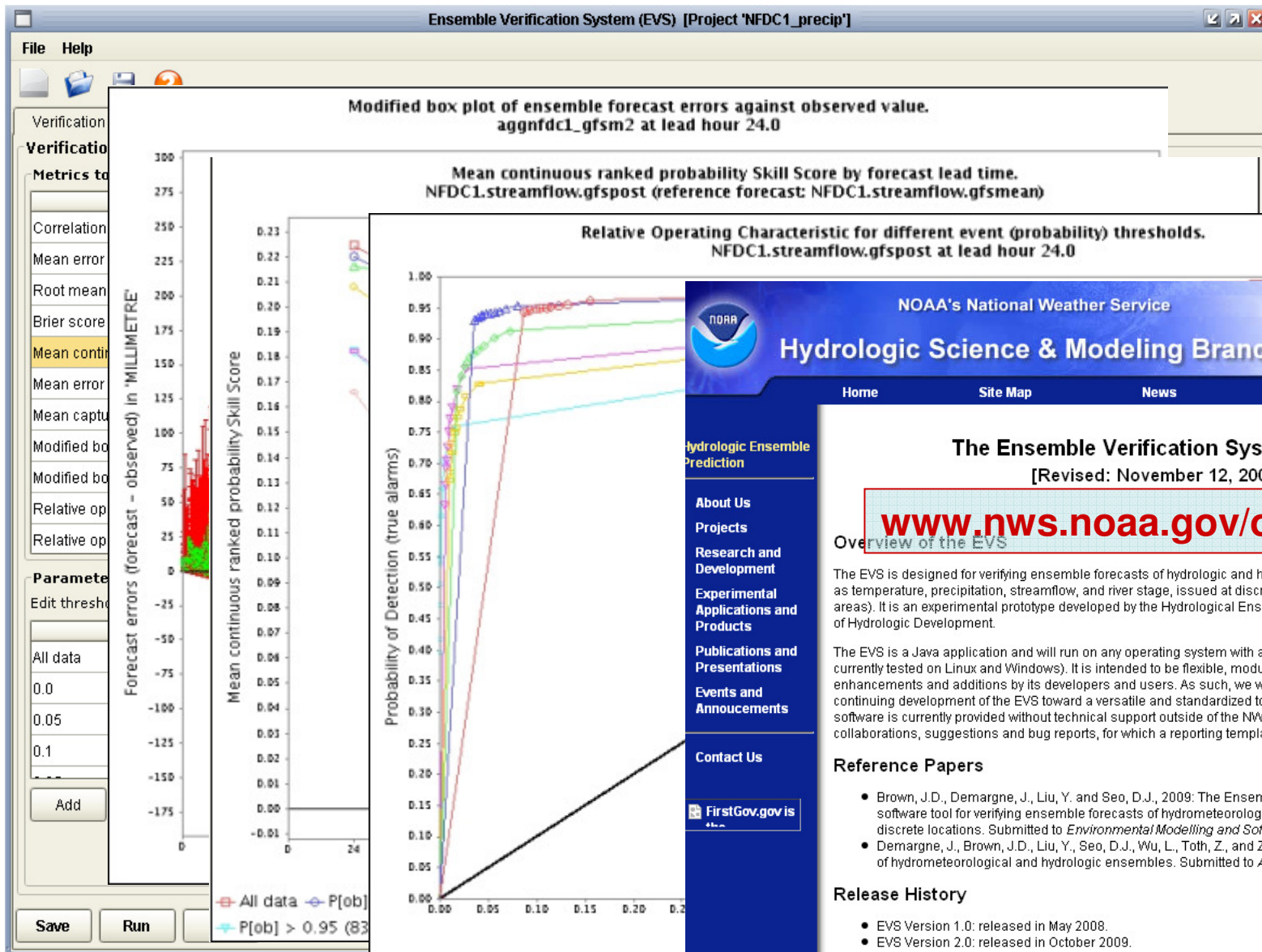


Flow regulations - A large challenge

Integration of Input and Hydrologic Uncertainties

An illustration of EPP-EnsPost approach





NOAA's National Weather Service
Hydrologic Science & Modeling Branch

Home Site Map News Organization

The Ensemble Verification System (EVS)
 [Revised: November 12, 2009]

www.nws.noaa.gov/oh/evs.html

Overview of the EVS

The EVS is designed for verifying ensemble forecasts of hydrologic and hydrometeorological variables, such as temperature, precipitation, streamflow, and river stage, issued at discrete forecast locations (points or areas). It is an experimental prototype developed by the Hydrological Ensemble Prediction group of the Office of Hydrologic Development.

The EVS is a Java application and will run on any operating system with a suitable Java Virtual Machine (it is currently tested on Linux and Windows). It is intended to be flexible, modular, and open to accommodate enhancements and additions by its developers and users. As such, we welcome your participation in the continuing development of the EVS toward a versatile and standardized tool for ensemble verification. The software is currently provided without technical support outside of the NWS. However, we welcome collaborations, suggestions and bug reports, for which a reporting template is provided with the distribution.

Reference Papers

- Brown, J.D., Demargne, J., Liu, Y. and Seo, D.J., 2009: The Ensemble Verification System (EVS): a software tool for verifying ensemble forecasts of hydrometeorological and hydrologic variables at discrete locations. Submitted to *Environmental Modelling and Software*.
- Demargne, J., Brown, J.D., Liu, Y., Seo, D.J., Wu, L., Toth, Z., and Zhu, Y., 2009: Diagnostic verification of hydrometeorological and hydrologic ensembles. Submitted to *Atmospheric Science Letters*.

Release History

- EVS Version 1.0: released in May 2008.
- EVS Version 2.0: released in October 2009.

Downloads

Version	Full Download	User's Manual	Executable	Release Notes	Test Data	Source Code	Developer Docs.	Bug Template
2.0 (10/16/09)	(25.4 MB)	(2.4 MB)	(13.3 MB)	(54 KB)	(1.7 MB)	(7.1 MB)	(1.5 MB)	(2 KB)

EVS interface, graphics and free download